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A DYNAMIC COMPONENT MODEL FOR FORECASTING HIGH-DIMENSIONAL REALIZED COVARIANCE MATRICES

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ISSN: 1971-3029

Publication date: September 30th, 2016

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A dynamic component model for forecasting high-dimensional realized covariance matrices *

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September 30, 2016

Abstract

The Multiplicative MIDAS Realized DCC (MMReDCC) model simultaneously accounts for short and long term dynamics in the conditional (co)volatilities of asset returns, in line with the empirical evidence suggesting that their level is changing over time as a function of economic conditions. Herein the applicability of the model is improved along two directions. First, by proposing an algorithm that relies on the maximization of an iteratively re-computed moment-based profile likelihood function and keeps estimation feasible in large dimensions by mitigating the incidental parameter problem. Second, by illustrating a conditional bootstrap procedure to generate multi-step ahead predictions from the model. In an empirical application on a dataset of forty-six equities, the MMReDCC model is found to statistically outperform the selected benchmarks in terms of in-sample fit as well as in terms of out-of-sample covariance predictions. The latter are mostly significant in periods of high market volatility.

Keywords: Realized covariance, dynamic component models, multi-step forecasting, iterative algorithm.

1 Introduction

Building models for predicting the volatility of high dimensional portfolios is important in risk management and asset allocation. Previous developments on time-varying covariances in large dimensions include the constant conditional correlation (CCC) model of Bollerslev (1990), where the volatilities of each asset are allowed to vary through time but the correlations are time invariant, the RiskMetrics model by JPMorgan (1994) and the DECO model by Engle and Kelly (2012), where pairwise correlations are assumed equal at a point in time, whilst being time varying. Recently, Andersen et al. (2001), Barndorff-Nielsen and

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^{*}The authors would like to thank Sébastien Laurent and Francesco Violante for providing the data used in the paper. Luc Bauwens and Manuela Braione acknowledge support of the "Communauté française de Belgique" through contract "Projet d'Actions de Recherche Concertées 12/17-045", granted by the "Académie universitaire Louvain". Giuseppe Storti acknowledges funding from the Italian Ministry of Education, University and Research (MIUR) through PRIN project "Forecasting economic and financial time series: understanding the complexity and modeling structural change" (code 2010J3LZEN).

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Shephard (2001) and Barndorff-Nielsen et al. (2011), among others, opened up a new channel for increasing the precision of covariance matrix estimates and forecasts by exploiting the information of high frequency asset returns. This development has motivated several researchers to investigate models directly fitted to series of realized covariance matrices (see Gouriéroux et al. (2009), Jin and Maheu (2013) and Chiriac and Voev (2011), to name a few).

Despite the superiority of these models, illustrated for example by Hautsch et al. (2015), there still remain technical and practical challenges one needs to deal with when constructing covariance matrix forecasts for high-dimensional systems. Primarily, the well-known "curse of dimensionality" problem, implying that the number of parameters grows as a power function of the cross-sectional model dimension. In order to save parameters, a simple solution is represented by the so called covariance (or correlation) targeting approach of Engle (2009), which consists in pre-estimating the constant intercept matrix in the model specification by linking it to the unconditional covariance matrix of returns. This method can be applied under the stationarity assumption of the model and is one of the most widely employed techniques to simplifying parameter estimation and reducing the computational burden when the numerical maximization of the likelihood function becomes difficult. However, in order to implement it, the user needs to have knowledge of the analytical relationship between the mean of the targeted process and the other model parameters. In many cases, due to the complex dependence structure encountered in the dynamic behavior of co-volatility matrices, this is far from being obvious (see Aielli (2013)). Moreover, even in cases in which targeting is feasible, severe homogeneity constraints still have to be imposed on the model parameters in order to make the model tractable for inference purposes (see e.g. Bauwens et al. (2016b)).

For their ability to separately analyze short and long run movements, component models have been effectively used in the Multivariate GARCH literature as a parsimonious way of describing this rich dynamic structure (see e.g. Colacito et al. (2011), Hafner and Linton (2010)). More recently, their applicability has been extended to dynamic models for realized covariance matrices by Golosnoy et al. (2012) and Bauwens et al. (2016a).

Herein we focus on the Multiplicative MIDAS Realized DCC (MMReDCC) model of Bauwens et al. (2016a), whose main ingredients are a multiplicative component structure, a Mixed Data Sampling (MIDAS)-type filter for modeling the secular dynamics and a short term parameterization directly inspired by the Dynamic Conditional Correlation (DCC) model of Engle (2002). For more detailed discussions of the DCC model and standard MIDAS regressions the reader can refer to Engle (2002), Ghysels et al. (2007) and references therein.

The choice of this particular model is supported by the following considerations. First, the multiplicative component structure entails specifying a unique long term factor for the whole covariance matrix, thus preserving tractability in the estimation process. Second, the MIDAS-type filter used in the specification of the secular component, compared to non-parametric smoothers, offers a much more convenient framework for the generation of multi-step ahead forecasts and potentially allows for the inclusion of external explanatory variables (such as low-frequency macroeconomic indicators). Also, if compared to other parametric alternatives, it represents an appealing compromise between parsimony and versatility. Finally, the short run DCC structure improves in flexibility over more basic linear recursions (e.g. the BEKK model by Engle and Kroner (1995)).

On an empirical ground, our choice is further supported by the results of the extensive out-of-sample forecasting comparison performed by Bauwens et al. (2016a). Although not identifying a unique winner, their findings show that the MMReDCC model gives remarkably good performances in important financial applications such as Value-at-Risk forecasting and portfolio allocation. Notwithstanding, their results are

limited to a relatively low dimensional setting (10 assets) and to a short term forecasting horizon (1 day).

This paper extends the applicability of the model along these directions: estimation for high-dimensional systems and multi-step forecasting. We contribute to the first line of research by developing a computationally feasible procedure for the estimation of vast dimensional MMReDCC models. In this respect, it is important to remark that, although the introduction of a dynamic secular component in the structure of the model adds a major element of flexibility and enables to obtain more accurate forecasts than standard models reverting to constant mean levels (see Bauwens et al. (2016a)), it also substantially increases the number of parameters to be estimated. Specifically, the long term component incorporates a scale intercept matrix with number of parameters equal to n(n+1)/2, where n denotes the number of assets. In a vast dimensional framework, this quickly translates into the impossibility of estimating the model since the intercept matrix cannot be directly targeted.

Therefore, we propose to overcome this estimation issue by proposing an iterative procedure inspired by the covariance targeting idea of Engle (2009). More precisely, based on a Method of Moments estimator, we profile out the parameters of the intercept matrix and iteratively maximize the likelihood in terms of the other parameters of interest. We refer to this as the Iterative Moment-Based Profiling (IMP) estimator, as opposed to the one-step Quasi Maximum Likelihood (QML) estimator which directly maximizes the likelihood function with respect to the full parameter vector.

It is worth noticing that the proposed estimation approach can be considered as a *switching algorithm* in the sense discussed by Boswijk (1995) and Cubadda et al. (2015), since the maximization of the overall likelihood is obtained by switching between optimizations over different blocks of parameters. This idea has a long standing tradition in the econometric analysis of time series. A simple, well known example of switching algorithm is given by the iterative Cochrane-Orcutt estimator. Compared to conventional switching algorithms, the approach that is here implemented incorporates an additional targeting step with the aim to reduce the dimension of the optimization problem by concentrating out some of the parameters by means of an iteratively re-computed moment-based estimator.

A comprehensive simulation study is performed to assess the finite-sample properties of the proposed estimator which is found to deliver unbiased estimates and to be computationally reliable despite the large number of parameters involved.

The second contribution of the paper is the development of a resampling based approach for the generation of multi-step ahead forecasts of the realized covariance matrices, which is motivated by the impossibility to derive a closed-form expression for the h-step predictor from the MMReDCC model. The bootstrap has been a standard tool for generating multi-step forecasts from non-linear and non-Gaussian time series models for more than two decades (see e.g. Clements and Smith (1997)). Its use has been later extended to univariate volatility modeling (see e.g. Pascual et al. (2006); Shephard and Sheppard (2010)) and more recently to the multivariate setting by Fresoli et al. (2015) and Fresoli and Ruiz (2015).

In the same spirit of Fresoli and Ruiz (2015), we propose a resampling algorithm making use of residual bootstrap with the appealing feature of being distribution-free, namely not relying on any particular assumption about the distribution of the realized covariance matrices. Differently from them, who generate multi-step forecasts from DCC models, our algorithm is adapted to the dynamic modeling of realized covariance matrices.

Two different applications are performed to illustrate the usefulness of the model on real data. In the first one, we focus on a low dimensional setting (ten assets), in which both the IMP and one-step QML estimation procedures are feasible, and compare the estimates obtained by means of both algorithms. We find that the IMP-based estimates are sufficiently close to the QML ones, so that using the IMP method in

large dimensions is a sensible approach. We further consider the case in which the IMP estimated parameters are used as starting values for the one-step QMLE: despite an increase in the maximized likelihood value, the improvement can be considered rather marginal, thus suggesting that the implementation of the IMP algorithm alone may be sufficient in practical applications.

In the second application, the MMReDCC model estimated for forty-six assets by the IMP method is used to generate forecasts of the realized covariance matrix up to twenty days ahead and compared to existing benchmarks not accounting for short and long term (co)volatility dynamics. It clearly emerges that over periods of relatively lower market volatility, where short and long run components are hardly distinguishable, simpler model specifications tend to be preferred especially at the shortest horizons. The opposite holds during more volatile periods, such as the one of the 2007-2008 financial crisis, where accounting for time-varying long term dynamics in the conditional covariance process appears crucial to generating superior forecasts. The latter are particularly sizeable at the longest horizons.

The remainder of the paper is organized as follows. Section 2 briefly recalls the structure of the MMReDCC model and explains the curse of dimensionality issue. Section 3 introduces the IMP algorithm and Section 4 presents the results of a Monte Carlo experiment aimed at assessing the finite sample statistical properties of the proposed estimation algorithm. The bootstrap procedure for computing multistep ahead forecasts is explained in Section 5, along with a simulation study to assess its finite sample behavior. Section 6 contains the empirical results for the in-sample estimation comparison and the out-of-sample forecasting exercise. Section 7 concludes with some final remarks.

2 The MMReDCC model

Let C_t be a $n \times n$ positive definite and symmetric (PDS) realized estimator of the latent integrated covariance matrix of daily returns. In the following, unless otherwise stated, we will refer to C_t as the realized covariance (RC), although any other consistent PDS estimator could be used. Conditionally on the set consisting of all relevant information up to and including day t-1, C_t is assumed to follow a n-dimensional central Wishart distribution:

$$C_t|I_{t-1} \sim W_n(\nu, S_t/\nu), \quad \forall t = 1, \dots, T,$$
 (1)

where ν (> n-1) is the degrees of freedom parameter and S_t is the PDS conditional mean matrix of order n. Under the assumption of absence of microstructure noise and other biases (see Barndorff-Nielsen and Shephard (2001)), S_t represents the conditional covariance matrix of returns, which is our object of interest.

In the MMReDCC model, S_t is designed to take into account the long run movements in the levels around which realized (co)variances (and by extension, correlations) fluctuate from day to day. To this extent, the model features a multiplicative decomposition of the conditional covariance matrix S_t into a smoothly varying or secular component $M_t=L_tL_t'$ and a short-lived component S_t^* , such that S_t can be rewritten as $S_t=L_t$ $S_t^*L_t'$, where the matrix square root L_t can be obtained by a Cholesky factorization of M_t . These components can then be modeled separately.

First, the secular component is specified parametrically and extracted by means of a MIDAS filter assumed to be a weighted sum of K lagged realized covariance matrices over a long horizon, where the number of lags spanned in the MIDAS specification is usually chosen to minimize the trade-off between the highest in-sample likelihood value and the number of observations lost to initialize the filter. It is

expressed as

$$M_t = \Lambda + \theta \sum_{k=1}^K \phi_k(\omega) C_{t-k}.$$
 (2)

In the right hand side of Eq.(2), the first term Λ is a $n \times n$ symmetric and semi-positive definite matrix of constant parameters, θ is a positive scalar and $\phi_k(\cdot)$ is a weight function parametrized according to the restricted Beta polynomial

$$\phi_k(\omega) = \frac{\left(1 - \frac{k}{K}\right)^{\omega - 1}}{\sum_{j=1}^K \left(1 - \frac{j}{K}\right)^{\omega - 1}}.$$

The scalar parameter ω determines the shape of the function and in order to achieve a time-decaying pattern of the weights, it is constrained to be larger than 1. For identification, the constraint $\sum_{k=1}^{K} \phi_k(\omega) = 1$ is imposed.

Second, the dynamics of the short term component S_t^* is specified according to a scalar DCC parametrization that enables a separate treatment of conditional volatilities and correlations. Letting X be any square matrix of arbitrary size n, in the remainder the notation $diag\{X\}$ is used to denote a $n \times n$ diagonal matrix with main diagonal elements equal to the corresponding diagonal elements of X. Therefore, assuming that $S_t^* = D_t^* R_t^* D_t^*$, where $D_t^* = diag\{S_t^*\}^{1/2}$, their scalar specifications correspond to the following equations:

$$S_{ii,t}^* = (1 - \gamma_i - \delta_i) + \gamma_i C_{ii,t-1}^* + \delta_i S_{ii,t-1}^*, \qquad \forall i = 1, \dots, n$$
(3)

$$R_t^* = (1 - \alpha - \beta)I_n + \alpha P_{t-1}^* + \beta R_{t-1}^*, \tag{4}$$

where $\gamma_i > 0$, $\delta_i \geq 0$, $\gamma_i + \delta_i < 1$, $\alpha > 0$, $\beta \geq 0$, $\alpha + \beta < 1$, $C_t^* = L_t^{-1}C_t(L_t')^{-1}$ and $P_t^* = (diag\{C_t^*\})^{-1/2}C_t^*(diag\{C_t^*\})^{-1/2}$. The matrix C_t^* is the realized covariance matrix purged of its long term component and the matrix P_t^* is the corresponding short term realized correlation matrix. Mean reversion to unity in Eq.(4) and to an identity matrix in Eq.(4) is needed for identification of the different components. Let $\gamma = \{\gamma_1, ..., \gamma_n\}$, $\delta = \{\delta_1, ..., \delta_n\}$ for further use.

The parameters can be estimated by maximizing the following Wishart (quasi) log-likelihood function in one step:

$$\ell_T(\psi) = -\frac{1}{2} \sum_{t=1}^{T} \left\{ \log |S_t(\psi)| + \text{tr}[S_t(\psi)^{-1}C_t] \right\}.$$
 (5)

The finite-dimensional parameter vector $\boldsymbol{\psi} = \{vech(\Lambda), \theta, \omega, \boldsymbol{\gamma}, \boldsymbol{\delta}, \alpha, \beta\}$, has length $\{n_{\Lambda} + 2n + 4\}$ where $n_{\Lambda} = n(n+1)/2 \sim O(n^2)$ denotes the number of unique parameters included in the intercept matrix Λ of Eq.(2). It is worth reminding that $\boldsymbol{\psi}$ does not include the degrees of freedom parameter ν , as the first order conditions for the estimation of the parameter vector $\boldsymbol{\psi}$ do not depend on ν (see Bauwens et al. (2016a)).

It is obvious that, as n increases, the curse of dimensionality problem quickly arises, leading to the number of parameters listed in the first two rows of Table 1. Observe that estimation becomes already cumbersome after n = 20 and almost impossible for $n \ge 50$.

Table 1: Number of parameters of MMReDCC models

Note: entries report the number of parameters as a function of the dimension n; n_{Λ} denotes the number of unique parameters contained in the Λ matrix, ψ denotes the full vector of model parameters and $\tilde{\psi}$ the vector of parameters excluding n_{Λ} .

	n=5	n = 10	n = 20	n = 50	n = 100
n_{Λ}	15	55	210	1275	5050
ψ	29	79	254	1379	5254
$ ilde{\psi}$	14	24	44	104	204

On the other hand, the last row of Table 1 shows that an obvious way to keep the model tractable is to avoid estimating the parameters of the matrix Λ . This would be sufficient to reduce the order to $2n + 4 \sim O(n)$, thus making the model estimable also for large n.

In the following section we put forward a feasible estimation procedure that aims at overcoming the direct estimation of the long term component intercept matrix, thus crucially mitigating the computational complexity of the model.

3 An Iterative Moment based Profiling (IMP) algorithm

In this section we discuss an iterative procedure for fitting the MMReDCC model to large dimensional datasets. The basic idea underlying the proposed algorithm is to eliminate from the likelihood maximization the parameters of the intercept matrix Λ using a technique that builds upon the covariance targeting discussed in Pedersen and Rahbek (2014) for BEKK and Engle et al. (2008) for DCC models. First of all, notice that from Eq.(2) and the following relation

$$\Lambda = E(M_t) - \theta \sum_{k=1}^{K} \phi_k(\omega) E(C_{t-k}),$$

a moment based estimator of the Λ intercept matrix is given by

$$\hat{\Lambda} = \frac{1}{T} \sum_{t=1}^{T} \left[M_t - \theta \sum_{k=1}^{K} \phi_k(\omega) C_{t-k} \right]. \tag{6}$$

Obviously, given the latent nature of M_t , the estimator in Eq.(6) cannot be computed in practice and hence the covariance targeting approach cannot be applied in the usual way. It is worth noticing that, if L_t and S_t^* were assumed to be independent, given $E(S_t^*) = I_n$, it would hold that $E(C_t) = E(M_t)$, implying that an asymptotically equivalent version of Eq.(6) could be explicitly computed by replacing M_t by C_t . However, this is not the approach we pursue, since the assumption of independence of the short and long term sources is difficult to justify and would result in a rather counterintuitive and arbitrary constraint. Hence, we adopt a different method.

It can be seen from Eq.(6) that no estimate of Λ makes sense regardless of the value of (θ, ω) , so that by making this dependence explicit, it is possible to obtain an estimate of Λ as a function of (θ, ω) , i.e. $\hat{\Lambda}(\theta, \omega)$. In this way, a different estimate of Λ is required for each different value of the other two

parameters. Therefore, by substituting $\hat{\Lambda}(\theta,\omega)$ for Λ in the Wishart QML function stated in Eq.(5), the following moment based QML approximation is obtained:

$$\tilde{\ell}_{T}(\tilde{\boldsymbol{\psi}}) = -\frac{1}{2} \sum_{t=1}^{T} \left\{ \log |\tilde{L}_{t}(\boldsymbol{\theta}, \omega) S_{t}^{*}(\tilde{\boldsymbol{\psi}}) \tilde{L}_{t}'(\boldsymbol{\theta}, \omega)| + \operatorname{tr}\left\{ [\tilde{L}_{t}(\boldsymbol{\theta}, \omega) S_{t}^{*}(\tilde{\boldsymbol{\psi}}) \tilde{L}_{t}'(\boldsymbol{\theta}, \omega)]^{-1} C_{t} \right\} \right\}$$

$$(7)$$

with $\tilde{\psi} = (\omega, \theta, \psi_{S^*})', \psi'_{S^*} = (\gamma, \delta, \alpha, \beta)$ and

$$\tilde{M}_t(\theta,\omega) = \tilde{L}_t(\theta,\omega)\tilde{L}_t'(\theta,\omega) = \hat{\Lambda}(\theta,\omega) + \theta \sum_{k=1}^K \phi_k(\omega)C_{t-k}.$$
(8)

The method we propose consists in estimating the parameters in $\tilde{\psi}$ by a block-wise maximization of the moment-based QML function given in Eq.(7). First, conditional on some reasonable initial guess of (θ, ω) , $\tilde{\ell}_T(\tilde{\psi})$ is maximized with respect to the short term parameters ψ_{S^*} and then, conditional on $\hat{\psi}_{S^*}$, the same function is maximized with respect to (θ, ω) . The procedure is iterated for $j = 0, \ldots, J$ until some convergence criterion on the likelihood is met.

To initialize the algorithm at j=0, one can reasonably use as starting values the parameter estimates obtained by fitting the model to low dimensional subsets of data; also, an initial guess for the long term component $M_{t,0}$ could be either provided in a naive way, *i.e.* using the series of observed realized covariance matrices directly, or in a more sophisticated manner, by fitting to the data a nonparametric kernel smoother with an optimized bandwidth parameter. Note that in order to guarantee the positive definiteness of $\tilde{M}_t(\theta,\omega)$ in Eq.(8), it suffices to initialize $M_{t,0}$ from a PDS matrix and to impose $\theta>0$. Given that the observed series of C_t , for every t, is PDS by definition, $\hat{\Lambda}(\theta,\omega)$ is assured to be at least semi-positive definite at each iteration j>0.

Once $\Lambda_j(\theta_j, \omega_j)$ has been computed at the initial iteration j = 0, for every j > 0 the steps conducted in the algorithm are as follows:

Step 1 Plug $\Lambda_{j-1}(\theta_{j-1},\omega_{j-1})$ into the dynamic equation for $\tilde{M}_{t,j}$ and $\tilde{L}_{t,j}=\operatorname{chol}(\tilde{M}_{t,j})$ for all t;

Step 2 For each asset i = 1, ..., n, obtain the short term GARCH(1,1) parameters as follows:

$$\left\{\hat{\gamma}_{i,j},\hat{\delta}_{i,j}\right\} = \underset{\left\{\gamma_{i},\delta_{i}\right\}}{\arg\max} \quad \tilde{\ell}_{T}\left(\theta_{j-1},\omega_{j-1},\alpha_{j-1},\beta_{j-1}\right);$$

Step 3 Conditional on the estimated vectors $\hat{\boldsymbol{\gamma}}_j = (\hat{\gamma}_{1,j}, \dots, \hat{\gamma}_{n,j})'$ and $\hat{\boldsymbol{\delta}}_j = (\hat{\delta}_{1,j}, \dots, \hat{\delta}_{n,j})'$, maximize the same log-likelihood function with respect to the short term DCC correlation parameters:

$$\{\hat{\alpha}_j, \hat{\beta}_j\} = \underset{\{\alpha, \beta\}}{\operatorname{arg max}} \quad \tilde{\ell}_T \left(\theta_{j-1}, \omega_{j-1}, \hat{\gamma}_j, \hat{\delta}_j\right);$$

Step 4 Conditionally on the vector of short term parameter estimates $\hat{\psi}_{S^*} = \{\hat{\gamma}_j, \hat{\delta}_j, \hat{\alpha}_j, \hat{\beta}_j\}$, maximize $\tilde{\ell}_T$ with respect to $\{\theta_j, \omega_j\}$; these estimates are used to compute an updated version of $\hat{\Lambda}_j(\theta_j, \omega_j)$;

Table 2: Simulation setting

In Panel A, for every i=1,...,n it holds $\{\gamma_i+\delta_i\}<1$. Entries of Panel B are scalar parameters chosen to initialize the algorithm in both sets of simulation exercises.

PANEL A:	Parameters				
θ			0.5		
K			264		
ω			15		
Λ			$\Lambda_{i,i} = 0.02,$	$\Lambda_{i,j} = 0.002$ for $i = 7$	$\neq j$
γ_i			$\sim U(\gamma_0 - 0)$	$.02, \gamma_0 + 0.02), \gamma_0 =$	= 0.2
δ_i			$\sim U(2\delta_0 + \gamma)$	$\gamma_i - 1 + 0.01, 1 - \gamma_i$	$(\delta_0 - 0.01), \delta_0 = 0.7$
α			0.2		
β			0.7		
ν			2n		
T			1000, 2000		
burn-in obs	servations		1000		
PANEL B:	Initial values				
θ_0	ω_0	$\gamma_{i,0}$	$\delta_{i,0}$	α_0	β_0
0.8	10	0.05	0.90	0.05	0.90

Step 5 Check for convergence, i.e. if

$$\left| \frac{\tilde{\ell}_T(\tilde{\boldsymbol{\psi}}_j) - \tilde{\ell}_T(\tilde{\boldsymbol{\psi}}_{j-1})}{\tilde{\ell}_T(\tilde{\boldsymbol{\psi}}_{j-1})} \right| < \epsilon, \quad \epsilon = 0.000001;$$

if convergence is achieved, the algorithm stops; otherwise update all parameter estimates and go back to Step 1.

It is worth to stress that although $\tilde{\ell}_T(\tilde{\psi})$ looks like a profile likelihood, it is not since $\hat{\Lambda}(\theta,\omega)$ is not a QML estimator but a feasible moment estimator. This motivates our choice to refer to Steps 1-5 as the Iterative Moment based Profiling algorithm, or IMP for short. This implies that $\tilde{\psi}$ is typically less efficient than the standard QML estimator that maximizes Eq.(5) in one step. We come back to this issue in Section 6.1.

4 Simulation study

A Monte Carlo study is conducted to analyze the finite sample properties of the IMP estimator. We assume the MMReDCC to be the DGP and we generate 500 time series of lengths T = 1000 and 2000 for n = 10, 20, 40 and 50, with true parameter values inspired by the estimates given in Bauwens et al. (2016a), as summarized in Table 2.

It is important to stress that, in order to initialize the algorithm, parameter values have to be carefully chosen. This is a standard requirement in every optimization procedure where the initial amount of information on the model parameters is limited. In our situation we are mainly concerned with the impact that different choices of $M_{t,0}$, more than the remaining set of parameters, may have on the convergence of the IMP algorithm. We evaluate this by performing a robustness check based on the two possible initializations of $M_{t,0}$ mentioned in Section 3.

In the first set of repetitions $M_{t,0}$ is computed by fitting to the series of simulated realized covariance matrices a Nadaraya-Watson kernel estimator with a single bandwidth parameter for the whole covariance

Table 3: Simulation exercise I: summary statistics

The table reports summary statistics of the first set of simulations where $M_{t,0}$ is initialized using a nonparametric kernel estimator, see Section 3. To save on space, $\bar{\gamma}$ and $\bar{\delta}$ are reported as averaged values across series and replications. RB denotes the Relative Bias computed over 500 replications. True parameter values used to simulate the process at the top of the table.

			T = 10	00			_				T=	2000		
	$ar{\gamma}$	$ar{\delta}$	α	β	θ	ω			$ar{\gamma}$	$ar{\delta}$	α	β	θ	ω_2
	0.197	0.705	0.2	0.7	0.5	15			0.197	0.705	0.2	0.7	0.5	15
			n=10)			_				n=10			
RB	0.098	-0.036	0.020	0.003	-0.058	-0.120	_	RB	-0.039	-0.002	0.033	0.003	0.053	-0.095
IQR	0.048	0.093	0.006	0.010	0.044	1.641		IQR	0.032	0.068	0.006	0.008	0.037	1.819
Mean	0.202	0.699	0.204	0.702	0.475	14.820		Mean	0.2	0.713	0.207	0.702	0.526	13.58
Min	0.176	0.660	0.191	0.679	0.393	7.460		Min	0.153	0.669	0.183	0.523	0.072	1.949
Max	0.214	0.735	0.220	0.728	0.709	18.943		Max	0.22	0.803	0.37	0.817	1.000	17.74
			n=20)			_				n=20			
RB	0.049	-0.009	0.019	0.001	-0.056	-0.110	_	RB	0.036	0.011	0.024	0.002	-0.014	-0.080
IQR	0.046	0.083	0.003	0.006	0.019	0.713		IQR	0.031	0.079	0.002	0.004	0.015	0.622
Mean	0.202	0.701	0.204	0.701	0.472	14.782		Mean	0.209	0.708	0.205	0.702	0.496	13.801
Min	0.171	0.633	0.197	0.687	0.430	12.802		Min	0.197	0.678	0.200	0.694	0.001	2.440
Max	0.219	0.744	0.211	0.711	0.532	16.759		Max	0.221	0.739	0.220	0.748	0.598	15.270
			n=40)							n=40			
RB	0.028	0.023	0.015	0.002	-0.049	-0.080	_	RB	0.033	0.029	0.022	0.002	-0.014	-0.072
IQR	0.042	0.077	0.002	0.002	0.011	0.372		IQR	0.030	0.064	0.001	0.002	0.007	0.263
Mean	0.208	0.715	0.203	0.701	0.476	14.810		Mean	0.209	0.719	0.204	0.702	0.493	13.925
Min	0.190	0.656	0.060	0.695	0.446	3.735		Min	0.181	0.671	0.182	0.674	0.172	1.000
Max	0.217	0.762	0.222	0.799	0.705	16.500		Max	0.221	0.761	0.223	0.744	0.837	14.760
			n=50)							n=50			
RB	0.027	0.011	0.016	0.001	-0.045	0.012		RB	0.029	0.027	0.017	0.001	-0.011	-0.037
IQR	0.042	0.076	0.001	0.002	0.008	0.293		IQR	0.030	0.056	0.001	0.002	0.007	0.220
Mean	0.208	0.716	0.203	0.701	0.473	15.182		Mean	0.208	0.720	0.203	0.701	0.494	14.442
Min	0.162	0.644	0.200	0.697	0.455	13.150		Min	0.191	0.657	0.199	0.695	0.474	12.089
Max	0.220	0.814	0.207	0.705	0.525	15.830		Max	0.222	0.763	0.207	0.707	0.529	16.238

matrix. As in Bauwens et al. (2016a) and Bauwens et al. (2013), the optimal bandwidth is selected by a least squares cross-validation criterion, where the six-month rolling covariance is used as the reference for the computation of least squares. In the second (equivalent) simulation study, $M_{t,0}$ is obtained by substituting in Eq. (6) the observed C_t for the latent matrix M_t at each t. In both cases, the initial scalar model parameters are set equal to the values listed in Panel B of Table 2. The estimation bias is evaluated by the relative bias (RB), computed as $\frac{1}{500} \sum_{i=1}^{500} \frac{\hat{\psi}_i - \psi}{\psi}$, along with the interquartile range (IQR), mean, minimum and maximum of the obtained parameter estimates. To save space, we report averaged bias results for the parameters of the MIDAS intercept matrix in a separate table.

Table 3 reports results from the first simulation exercise. As expected, the relative biases decrease as n or T increases. The biases for the parameters of the short term volatility and correlation components are very small, being smaller than five per cent in most of the cases, with one exception recorded for $\bar{\gamma}$ at T=1000 for n=10. As for the scalar parameters in the MIDAS specification, the bias for θ is negative in seven out of eight cases (the exception occurs for n=10 at T=2000) and ranging from the maximum of 5.8% (in absolute value) for n=10 and T=1000 to the lowest value of 1.1% for n=50 and T=2000. The bias on the ω parameter, also generally negative, tends to decrease with n but is usually of higher order (from 1.1 to 12% in absolute value). A similar behavior is observed for the IQR measure, which decreases

Table 4: Simulation exercise II: summary statistics

The table reports summary statistics of the second set of simulations where $M_{t,0}$ is initialized from the series of realized covariance matrices, see Section 3. To save on space, $\bar{\gamma}$ and $\bar{\delta}$ are reported as averaged values across series and replications. RB denotes the Relative Bias computed over 500 replications. True parameter values used to simulate the process at the top of the table.

	$egin{array}{cccccccccccccccccccccccccccccccccccc$								-			2000		
	$\bar{\sim}$				θ	(,)			$\bar{\gamma}$	$ar{\delta}$	α	β	θ	ω
	0.197	0.705	0.2	0.7	0.5	15			0.197	0.705	0.2	0.7	0.5	1
	0.101	0.100	n=10		0.0		-		0.101	n=			0.0	
RB	-0.077	0.013	0.019	0.002	-0.032	-0.007	-	$\overline{\mathrm{RB}}$	0.043	0.006	0.025	0.002	-0.012	-0.0
IQR	0.070	0.113	0.007	0.010	0.043	1.664		IQR	0.028	0.046	0.004	0.007	0.024	0.8
Mean	0.191	0.708	0.204	0.701	0.484	14.892		Mean	0.211	0.707	0.205	0.701	0.494	13.9
Min	0.107	0.588	0.191	0.678	0.393	6.678		Min	0.189	0.654	0.196	0.686	0.435	9.6
Max	0.231	0.833	0.218	0.723	0.927	19.237		Max	0.232	0.748	0.213	0.715	0.623	15.5
	0.202	0.000	n=20		0.0_,		-		0.202	n=		0	0.020	
RB	0.048	-0.002	0.018	0.002	-0.045	-0.008	-	$\overline{\mathrm{RB}}$	0.006	0.039	0.023	0.002	-0.011	-0.0
IQR	0.042	0.085	0.003	0.005	0.021	0.719		IQR	0.030	0.060	0.002	0.004	0.013	0.5
Mean	0.207	0.702	0.204	0.701	0.477	14.887		Mean	0.206	0.721	0.205	0.701	0.494	14.0
Min	0.196	0.649	0.197	0.689	0.429	6.751		Min	0.164	0.680	0.199	0.692	0.467	11.
Max	0.220	0.740	0.214	0.713	0.887	16.573		Max	0.225	0.772	0.209	0.710	0.555	15.5
			n=40)			-	-		n=	40			
RB	0.046	0.017	0.017	0.003	-0.045	0.005	-	$\overline{\mathrm{RB}}$	0.050	0.016	0.021	0.002	-0.012	-0.0
IQR	0.042	0.080	0.002	0.003	0.010	0.421		IQR	0.029	0.053	0.001	0.002	0.007	0.2
Mean	0.209	0.713	0.203	0.702	0.477	15.078		Mean	0.210	0.718	0.204	0.701	0.494	14.
Min	0.197	0.682	0.193	0.696	0.116	6.895		Min	0.194	0.658	0.202	0.697	0.479	8.4
Max	0.219	0.756	0.216	0.807	0.955	49.985		Max	0.223	0.768	0.212	0.708	0.726	14.0
			n=50)			-			n=	50			
RB	0.029	0.028	0.016	0.002	-0.053	0.015	-	$\overline{\mathrm{RB}}$	0.028	0.018	0.020	0.002	-0.017	-0.0
IQR	0.041	0.071	0.001	0.002	0.009	0.342		IQR	0.030	0.061	0.001	0.001	0.005	0.1
Mean	0.208	0.715	0.203	0.701	0.473	15.225		Mean	0.208	0.721	0.204	0.701	0.492	14.2
Min	0.190	0.632	0.200	0.698	0.457	14.190		Min	0.184	0.674	0.202	0.698	0.437	11.
Max	0.220	0.766	0.206	0.705	0.494	15.844		Max	0.216	0.766	0.209	0.713	0.508	14.

across n and T but remains on higher values for the parameter ω . However, this does not represent a major concern as the Beta weight function is not very sensitive to small variations of this parameter and therefore we do not expect the likelihood function to be either.

Table 4 gives an idea of the robustness of the results to the other initialization of the long term component. Entries can be directly compared to those in Table 3. As hoped for, the initial choice has a minor impact on the overall accuracy of the estimator, as the parameter biases are in the same range of magnitude and the comments made earlier are still valid under this alternative scenario.

Figure 1 contains plots of the Monte Carlo standard deviations of the estimated θ, ω, α and β parameters against the cross-section size. In all cases, standard deviations tend to decline as the cross-section dimension grows, with a faster decline when T=2000. The two approaches produce similar parameter standard deviations, with slightly bigger values recorded for θ and ω under the second simulation experiment in correspondence with the higher cross-section sizes.

If we move to analyzing the bias results for the scale MIDAS intercept matrix, Table 5 shows that under both sets of simulation exercises the estimator $\hat{\Lambda}(\theta,\omega)$ well approximates the true Λ matrix at all cross-section dimensions, with the parameter bias (averaged across diagonal and off-diagonal elements) clearly improving with increasing n and T. Again, the direct comparison of Panels A and B confirms that

Table 5: Bias results for the scale MIDAS intercept matrix

Panel A reports summary statistics of the first simulation exercise where $M_{t,0}$ is initialized from a nonparametric smoother while Panel B reports results from the second simulation exercise where the series of observed realized covariance matrices are used. $RB_{\{i,i\}}$ denotes averaged values over diagonal terms, while $RB_{\{i,j\}}$ denotes averages over off diagonal terms. Number of simulations is 500.

Pane	L A: SIMUL	ATION EXERCI	se I
T=10	00	T=2	000
n=1	0	n=	10
$RB_{\{i,i\}}$	0.080	$RB_{\{i,i\}}$	0.033
$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.079	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.002
n=2	0	n=1	20
$\overline{\mathrm{RB}_{\{\mathrm{i},\mathrm{i}\}}}$	0.073	$RB_{\{i,i\}}$	0.068
$RB_{\{i,j\}}$	0.062	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.048
n=4	0	n=	40
$\overline{\mathrm{RB}_{\{\mathrm{i},\mathrm{i}\}}}$	0.073	$RB_{\{i,i\}}$	0.062
$RB_{\{i,j\}}$	0.061	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.046
n=5	0	n=	50
$\overline{\mathrm{RB}_{\{\mathrm{i},\mathrm{i}\}}}$	0.072	$RB_{\{i,i\}}$	0.004
$RB_{\{i,i\}}$	0.057	$RB_{\{i,i\}}$	0.037

Pane	L B: SIMUL	ATION EXERCIS	SE II
-	T=1000	T=2	000
	n=10	n=	10
$RB_{\{i,i\}}$	0.075	$\mathrm{RB}_{\{\mathrm{i,i}\}}$	0.060
$RB_{\{i,j\}}$	0.066	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.040
	n=20	n=2	20
$\overline{\mathrm{RB}_{\{\mathrm{i},\mathrm{i}\}}}$	0.072	$RB_{\{i,i\}}$	0.058
$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.060	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.044
	n=40	n=	40
$RB_{\{i,i\}}$	0.073	$\mathrm{RB}_{\{\mathrm{i,i}\}}$	0.058
$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.159	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.043
	n=50	n=0	50
$RB_{\{i,i\}}$	0.072	$\mathrm{RB}_{\{\mathrm{i},\mathrm{i}\}}$	0.058
$RB_{\{i,j\}}$	0.058	$\mathrm{RB}_{\{\mathrm{i},\mathrm{j}\}}$	0.043

the algorithm initialized from the series of realized covariance matrices overall performs no worse than the one initialized from a nonparametric smoother.

Finally, as the final interest is in the overall accuracy of the model in fitting conditional (co)variances and correlations (as a referee pointed out to us), we complement this section with an additional table that extends the Monte Carlo study to analyze the properties of the estimated in-sample series. Specifically, for each of the two exercises performed, we compare simulated and estimated variances, covariances and correlations in terms of mean, standard deviation, lower and upper quartiles. Moreover, we compare the performance, in terms of variability, of the equally weighted portfolios constructed employing the true and the estimated conditional covariance matrix. Table 6 illustrates the strong similarity between the true series and the series obtained using the estimated model parameters, which supports the set of results discussed previously. Once again, no substantial difference can be detected between the two panels indexing the chosen initialization approach.

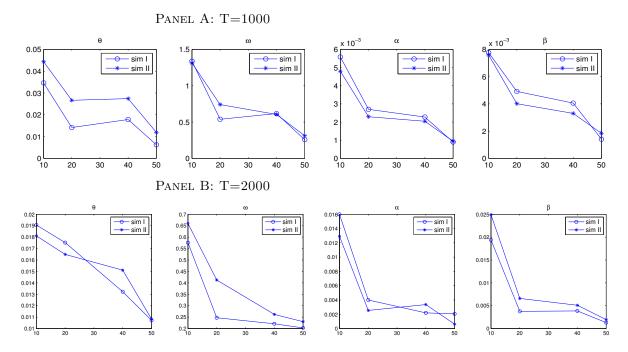
To summarize, the simulation study carried out in this section suggests that the proposed algorithm works accurately in finite samples and converges irrespective of the initialization choice made for the M_t matrices. Overall, the moment-based estimator used for iteratively targeting the constant intercept matrix in the secular component does not create a severe bias problem in the estimation of the other parameters, thus representing a feasible solution to alleviate the curse of dimensionality issue that would otherwise prevent the use of the MMReDCC model in high dimensional applications. Both initialization methods for $M_{t,0}$ can be used in practice. In the empirical section, we have opted for the nonparametric smoother.

5 Multi-step Forecasting

Models featuring short and long run dynamics are particularly relevant for computing multi-step-ahead predictions, as their dynamic component structure is conceivably expected to be beneficial for long term

Figure 1: IMP Monte Carlo standard deviations

The figure shows standard deviations of the IMP Monte Carlo estimated scalar parameters θ, ω, α and β against the cross-section dimension ranging from 10 to 50. Results from the first (Sim. I) and second (Sim. II) simulation study are jointly reported in Panel A for T=1000 and Panel B for T=2000.



forecasts. Unfortunately, the complex nonlinear structure of the MMReDCC model prevents the analytical derivation of closed-form solutions. In order to overcome this limit, we compute multi-step predictions by means of a procedure based on bootstrap resampling. Subsection 5.1 formally introduces the procedure while the next one investigates its properties in finite samples.

5.1 A conditional bootstrap (CB) procedure

At the outset, notice that Eq.(1) implies that $E(C_t|\Im_{t-1}) = S_t$, so that C_t can be represented as

$$C_t = S_t^{1/2} U_t (S_t^{1/2})', (9)$$

where U_t is an element of a sequence of iid random matrices with $E(U_t) = I_n$, and $S_t^{1/2}$ denotes the lower-triangular Cholesky factor of S_t such that $S_t^{1/2}(S_t^{1/2})' = S_t$. If $U_t \sim W_n(\nu, I_n/\nu)$, the Wishart assumption of Eq.(1) is recovered, but this is not needed to justify the bootstrap procedure used for generating multi-step-ahead forecasts of the realized covariance matrix C_t . The procedure is described in the following six steps.

Step 1 Estimate the model on $\{C_t, t = 1, ..., T\}$ and obtain the parameter vector $\hat{\boldsymbol{\psi}} = \{vech(\hat{\Lambda}), \hat{\theta}, \hat{\omega}, \hat{\boldsymbol{\gamma}}, \hat{\boldsymbol{\delta}}, \hat{\alpha}, \hat{\beta}\}$ to compute the estimated conditional covariance \hat{S}_t .

Step 2 Compute the estimated residuals

$$\hat{U}_t = \hat{S}_t^{-1/2} C_t (\hat{S}_t^{-1/2})', \qquad t = 1, \dots, T$$

Table 6: Properties of the estimator

The table shows summary statistics of simulated (True) and estimated variance, covariance and correlation series, with values reported as averages across assets (n) and simulations (500). Sim I denotes the first simulation exercise where $M_{t,0}$ is initialized from a nonparametric smoother while Sim II uses the series of realized covariance matrices. In the last two columns we compare the properties of the volatilities of the n-dimensional equally weighted portfolios constructed using the true and the estimated conditional covariance matrix at each t. Q1 and Q3 respectively denote the first (0.25) and the third (0.75) quartile.

n	Т	Stat.		Volatility	/ (e-03)		Covariano	ce (e-03)		Correl	ation	P	ortf. vola	tility
			True	Sim .I	Sim .II	True	Sim .I	Sim .II	True	Sim .I	Sim .II	True	Sim .I	Sim .II
10	1000	Mean	0.924	0.932	0.938	0.109	0.109	0.110	0.116	0.116	0.118	0.014	0.014	0.015
		Std	0.217	0.220	0.230	0.148	0.149	0.147	0.149	0.148	0.145	0.002	0.002	0.001
		Q1	0.765	0.771	0.757	0.010	0.010	0.011	0.011	0.012	0.012	0.013	0.013	0.014
		Q3	1.050	1.060	1.059	0.203	0.204	0.205	0.223	0.222	0.243	0.015	0.015	0.016
	2000	Mean	0.995	1.006	0.962	0.156	0.157	0.157	0.151	0.150	0.148	0.014	0.014	0.014
		Std	0.172	0.181	0.202	0.118	0.122	0.121	0.114	0.115	0.117	0.001	0.001	0.001
		Q1	0.836	0.840	0.827	0.060	0.059	0.058	0.062	0.060	0.061	0.014	0.014	0.013
		Q3	1.128	1.145	1.150	0.244	0.247	0.220	0.240	0.240	0.238	0.015	0.015	0.015
20	1000	Mean	0.963	0.971	0.972	0.136	0.136	0.136	0.139	0.138	0.138	0.013	0.013	0.013
		Std	0.157	0.161	0.162	0.110	0.111	0.111	0.108	0.108	0.108	0.001	0.001	0.001
		Q1	0.828	0.833	0.832	0.055	0.055	0.055	0.060	0.060	0.060	0.013	0.013	0.013
		Q3	1.075	1.086	1.087	0.210	0.211	0.212	0.218	0.218	0.218	0.014	0.014	0.014
	2000	Mean	0.963	0.973	1.002	0.136	0.137	0.157	0.139	0.138	0.152	0.013	0.013	0.014
		Std	0.161	0.168	0.158	0.113	0.115	0.107	0.111	0.111	0.101	0.001	0.001	0.001
		Q1	0.828	0.832	0.854	0.055	0.055	0.072	0.060	0.059	0.075	0.013	0.013	0.013
		Q3	1.075	1.089	1.128	0.210	0.212	0.235	0.218	0.218	0.230	0.014	0.014	0.014
40	1000	Mean	1.040	1.048	1.294	0.188	0.189	0.235	0.176	0.175	0.178	0.014	0.015	0.015
		Std	0.123	0.131	0.115	0.087	0.088	0.085	0.079	0.079	0.076	0.001	0.001	0.001
		Q1	0.894	0.896	0.902	0.102	0.103	0.106	0.106	0.106	0.109	0.014	0.014	0.014
		Q3	1.168	1.181	1.285	0.262	0.264	0.288	0.245	0.244	0.248	0.015	0.015	0.015
	2000	Mean	1.046	1.042	1.059	0.191	0.198	0.195	0.178	0.179	0.179	0.015	0.015	0.015
		Std	0.123	0.125	0.129	0.088	0.089	0.088	0.078	0.078	0.078	0.001	0.001	0.001
		Q1	0.899	0.876	0.905	0.106	0.109	0.107	0.109	0.109	0.110	0.014	0.014	0.014
		Q3	1.176	1.057	1.194	0.266	0.274	0.271	0.247	0.251	0.248	0.015	0.015	0.015
50	1000	Mean	1.078	1.086	1.098	0.212	0.213	0.221	0.191	0.190	0.195	0.015	0.015	0.015
		Std	0.115	0.123	0.120	0.082	0.082	0.080	0.071	0.071	0.068	0.001	0.001	0.001
		Q1	0.918	0.920	0.928	0.118	0.118	0.124	0.119	0.119	0.124	0.015	0.015	0.015
		Q3	1.222	1.234	1.249	0.294	0.296	0.304	0.262	0.261	0.266	0.016	0.016	0.016
	2000	Mean	1.088	1.098	1.088	0.219	0.220	0.214	0.195	0.195	0.191	0.015	0.015	0.015
		Std	0.114	0.121	0.123	0.082	0.083	0.084	0.070	0.070	0.072	0.001	0.001	0.001
		Q1	0.925	0.928	0.922	0.123	0.123	0.119	0.124	0.123	0.120	0.015	0.015	0.015
		Q3	1.235	1.249	1.235	0.302	0.304	0.295	0.266	0.265	0.261	0.016	0.016	0.016

and rescale them to enforce their sample mean to be equal to I_n :

$$\tilde{U}_t = (\hat{E}_u^{-1/2})\hat{U}_t(\hat{E}_u^{-1/2})',$$

where $\hat{E}_u = (1/T) \sum_{t=1}^T \hat{U}_t$. The rescaled \tilde{U}_t can then be used to generate bootstrap replicates of C_{T+j} , for $j = 1, \ldots, h$, where h denotes the chosen forecast horizon.

Step 3 Draw with replacement a bootstrap sample $\{\tilde{U}_{T+1|T}, \dots, \tilde{U}_{T+h|T}\}$ of length h from the empirical CDF of $\{\tilde{U}_t, t = 1, \dots, T\}$.

Step 4 Initialize the procedure at C_T , \hat{R}_T^* , \hat{P}_T^* , \hat{S}_T^* and \hat{L}_T . For $j=1,\ldots,h$, recursively generate a sequence

of bootstrap replicates of C_{T+j} as follows:

$$\begin{split} R_{T+j|T}^* &= (1-\hat{\alpha}-\hat{\beta})I_n + \hat{\alpha}P_{T+j-1|T}^* + \hat{\beta}R_{T+j-1|T}^*, \\ S_{ii,T+j|T}^* &= (1-\hat{\gamma}_i - \hat{\delta}_i) + \hat{\gamma}_i C_{ii,T+j-1|T}^* + \hat{\delta}_i S_{ii,T+j-1|T}^*, \\ S_{T+j|T}^* &= (diag\{S_{T+j|T}^*\})^{1/2} R_{T+j|T}^* (diag\{S_{T+j|T}^*\})^{1/2}, \\ S_{T+j|T} &= L_{T+j|T} S_{T+j|T}^* L_{T+j|T}', \\ C_{T+j|T} &= S_{T+j|T}^{1/2} \tilde{U}_{T+j|T} (S_{T+j|T}^{1/2})', \\ M_{T+j|T} &= \hat{\Lambda}(\theta, \omega) + \hat{\theta} \sum_{k=1}^K \phi_k(\hat{\omega}) C_{T-k+j|T}, \\ L_{T+j|T} &= M_{T+j|T}^{1/2}, \\ C_{T+j|T}^* &= L_{T+j|T}^{-1} C_{T+j|T} (L_{T+j|T}')^{-1}, \\ P_{T+j|T}^* &= (diag\{C_{T+j|T}^*\})^{-1/2} C_{T+j|T}^* (diag\{C_{T+j|T}^*\})^{-1/2}. \end{split}$$

Step 5 Repeat steps 3–4 B times, where B is set sufficiently large (e.g. B=5000). As a result, the procedure generates an array of $h \times B$ bootstrap replicates $(C_{T+j|T}^{(1)}, \ldots, C_{T+j|T}^{(B)})$ for $C_{T+j|T}$.

Step 6 Finally, the h-steps-ahead forecast is obtained as

$$\hat{S}_{T,h} = \frac{1}{B} \sum_{b=1}^{B} C_{T+h|T}^{(b)}.$$

It is worth to mention that the proposed procedure is applied by conditioning on the estimated model parameters, namely by keeping fixed the parameter estimates in all bootstrap forecasts of C_{T+j} , for $j=1,\ldots,h$, such that the achieved bootstrap h-steps ahead prediction depends only on the resampled residuals. Clearly, this could be relaxed in order to account for the variability associated to parameter estimation by re-estimating ψ on each bootstrap replicate, but it would come at the not negligible cost of increasing computational complexity and time. Overall, the results presented in Section 5.2 provide sufficient evidence that our approach works fine in finite samples.

Finally, even if our primary interest is in forecasting from MMReDCC models, the proposed forecasting procedure is very general and can be readily adapted to any model that admits the representation in Eq.(9), where S_t is modeled as a function of past information \Im_{t-1} . For example, in the empirical application which is presented in Section 6.2, we also use it to generate multi-step ahead forecasts of C_t from the cRDCC model of Bauwens et al. (2012). To this purpose, the dynamic equations in step 4 must be replaced by those pertaining to the specific model of interest.

5.2 Finite sample properties

In order to analyze the finite sample behavior of the proposed bootstrap procedure, we devise a simple Monte Carlo experiment. Namely, we generate 1000 series with the MMReDCC model using the same simulation design used in Section 4, with the nonparametric smoother chosen as the initialization method

for $M_{t,0}$. Results obtained employing the alternative initialization approach are qualitatively similar and thus not reported for brevity. The sample sizes considered are T = 1000 and 2000 and the cross-sectional dimensions are n = 5, 10, 20 and 50. In each case, we generate $j = 1, \ldots, h$ future values of the simulated series, where h = 2, 10 and 20, that are considered as the reference forecasting sample.

For each obtained set of B bootstrap replicates $(C_{T+j|T}^{(1)}, \ldots, C_{T+j|T}^{(B)})$, we compute the corresponding prediction limits, defined as the quantiles of the bootstrap distribution function of $C_{T+j|T}^{(b)}$ ($b=1,\ldots,B$). More specifically, if $D_{c,B}(z)$ is an estimate of the distribution function $D_c(z) = Pr(C_{T+j|T} \leq z)$, then, a $100(1-\vartheta)\%$ prediction interval for C_{T+j} is achieved as

$$[L_{C,B}(z), U_{C,B}(z)] = \left[Q_{C,B}\left(\frac{\vartheta}{2}\right), Q_{C,B}\left(1 - \frac{\vartheta}{2}\right)\right],\tag{10}$$

with $Q_{C,B} = D_{c,B}^{-1}$. Bootstrap intervals are constructed based on B=999 replicates with nominal coverages $1 - \vartheta$ equal to 0.90, 0.95 and 0.99. After this, we compute the empirical coverage by counting the number of future values inside the corresponding intervals as $(1 - \vartheta)^* = \{L_{C,B} \leq C_{T+j} \leq U_{C,B}\}$. In addition we compute left and right coverage as the proportion of predictions falling below $L_{C,B}$ and above $U_{C,B}$, respectively.

Results are reported in Table 7 as averages across univariate variance (left panel) and covariance (right panel) series. First of all, we can notice that results are qualitatively similar across the two panels. It emerges that the intervals for future volatilities and covolatilities at multiple-steps ahead have average coverages close to the nominal values, and that their performance improves as the sample size increases from 1000 to 2000 observations.

The table also shows that the coverage rates depend on the forecast horizon, and that they have a tendency to decrease as horizons increase. This comes as a consequence of the parameter estimation variability that is not accounted for, as well as from the addition of error uncertainty. However, even if for h > 2 there is a slight undercoverage, coverage values are never below their nominal levels by more than 2.7%, and this happens irrespective of the forecast horizon or the considered sample size.

Overall, Monte Carlo results show that the proposed bootstrap procedure is capable of generating accurate point and interval forecasts from the MMReDCC model.

6 Empirical Applications

This section contains two empirical applications. The first application provides the estimation results for the IMP estimator in comparison with the standard QML estimator in the ideal case where both can be computed. The second one is performed in a large dimensional system and aims at evaluating both the full-sample fit of the model and its forecasting performance. Specifically, we evaluate the ability of the MMReDCC model to provide accurate multi-steps-ahead covariance predictions against existing competitors not accounting for time-varying long term dynamics.

6.1 Small sample accuracy comparison

In small dimensional applications, according to Table 1, the QMLE is applicable and represents the most efficient estimator, at least asymptotically. Hence, a simple way to evaluate the in-sample performance of the proposed approach, is to compare the estimates provided by the IMP method to those obtained by

 $\label{eq:Table 7: Prediction intervals} Table \ 7: \ \textbf{Prediction intervals}$ The table reports prediction intervals for variances (left panel) and covariances (right panel) of MMReDCC model across 1000 simulations. tions.

_	T 1	nr.		RIANCES	A	A	- -	Lead	Т		Average	Av.cov.	Av.co
n	Lead	\mathbf{T}		Average		Av.cov.	. п	time	1		coverage	below	above
	time	1000		coverage	below	above	- 5	2	1000	0.90	0.897	0.052	0.051
j	2	1000	0.90	0.891	0.054	0.054	0	2	1000	0.95	0.946	0.032	0.026
			0.95 0.99	0.945 0.978	0.026 0.008	0.029 0.014				0.99	0.981	0.007	0.011
		2000	0.99	0.894	0.053	0.014			2000	0.90	0.906	0.046	0.048
		2000	0.95	0.951	0.033	0.035				0.95	0.954	0.025	0.021
			0.99	0.982	0.005	0.012				0.99	0.982	0.007	0.011
	10	1000	0.90	0.878	0.064	0.059		10	1000	0.90	0.877	0.061	0.062
			0.95	0.932	0.036	0.032				0.95	0.930	0.035	0.035
			0.99	0.971	0.012	0.017				0.99	0.974	0.010	0.016
		2000	0.90	0.882	0.057	0.061			2000	0.90	0.882	0.060	0.058
			0.95	0.935	0.030	0.034				0.95	0.935	0.035	0.031
			0.99	0.973	0.009	0.018				0.99	0.978	0.010	0.013
	20	1000	0.90	0.873	0.062	0.065		20	1000	0.90	0.874	0.065	0.061
			0.95	0.932	0.033	0.035				0.95	0.930	0.036	0.036
			0.99	0.977	0.006	0.017			2000	0.99	0.973	0.010	0.017
		2000	0.90	0.874	0.067	0.065			2000	0.90	0.879	0.064	0.057
			0.95	0.923	0.035	0.041				0.95	0.933	0.036	0.034
_		1000	0.99	0.970	0.008	0.022		2	1000	0.99	0.971	0.012	0.018
0	2	1000	0.90	0.891	0.053	0.057	10	2	1000	$0.90 \\ 0.95$	0.889 0.943	0.056 0.028	0.055 0.029
			0.95 0.99	0.940 0.979	0.028 0.007	0.031 0.015				0.99	0.943	0.028	0.028
		2000	0.99	0.979	0.054	0.013 0.052			2000	0.90	0.895	0.053	0.013
		2000	0.90	0.893	0.034 0.027	0.032			2000	0.95	0.946	0.028	0.037
			0.99	0.943	0.027	0.023				0.99	0.981	0.007	0.012
	10	1000	0.90	0.876	0.060	0.064		10	1000	0.90	0.883	0.060	0.058
			0.95	0.933	0.030	0.037				0.95	0.935	0.032	0.033
			0.99	0.975	0.007	0.018				0.99	0.975	0.010	0.016
		2000	0.90	0.883	0.060	0.057			2000	0.90	0.880	0.058	0.060
			0.95	0.938	0.030	0.030				0.95	0.935	0.032	0.032
			0.99	0.978	0.006	0.014				0.99	0.977	0.009	0.014
	20	1000	0.90	0.873	0.065	0.066		20	1000	0.90	0.873	0.064	0.063
			0.95	0.930	0.033	0.037				0.95	0.932	0.037	0.03
			0.99	0.975	0.007	0.018				0.99	0.973	0.011	0.016
		2000	0.90	0.876	0.060	0.063			2000	0.90	0.870	0.063	0.064
			0.95	0.930	0.033	0.037				0.95	0.934	0.035	0.038
_		1000	0.99	0.974	0.008	0.017			1000	0.99	0.972	0.010	0.017
0	2	1000	0.90	0.892	0.049	0.059	20	2	1000	0.90	0.886	0.057	0.057
			0.95 0.99	0.943 0.981	0.025 0.006	0.032 0.014				$0.95 \\ 0.99$	0.939 0.979	$0.030 \\ 0.007$	0.031 0.013
		2000	0.90	0.892	0.051	0.014			2000	0.99	0.887	0.007	0.01
		2000	0.95	0.946	0.026	0.029			2000	0.95	0.940	0.030	0.030
			0.99	0.983	0.005	0.012				0.99	0.979	0.007	0.030
	10	1000	0.90	0.880	0.055	0.065		10	1000	0.90	0.876	0.062	0.062
			0.95	0.935	0.029	0.036				0.95	0.931	0.034	0.034
			0.99	0.976	0.007	0.017				0.99	0.975	0.009	0.016
		2000	0.90	0.883	0.054	0.063			2000	0.90	0.876	0.061	0.062
			0.95	0.936	0.028	0.036				0.95	0.932	0.034	0.034
			0.99	0.975	0.008	0.017				0.99	0.975	0.009	0.016
	20	1000	0.90	0.877	0.060	0.063		20	1000	0.90	0.873	0.066	0.068
			0.95	0.933	0.032	0.036				0.95	0.930	0.037	0.038
			0.99	0.972	0.009	0.019				0.99	0.970	0.011	0.018
		2000	0.90	0.877	0.059	0.064			2000	0.90	0.875	0.065	0.066
			0.95	0.933	0.033	0.034				0.95	0.931	0.037	0.037
_		1000	0.99	0.977	0.007	0.016				0.99	0.972	0.011	0.01
)	2	1000	0.90	0.899	0.045	0.056	50	2	1000	0.90	0.886	0.057	0.057
			0.95 0.99	0.950 0.985	0.023 0.005	0.027 0.010				0.95	0.939	0.030	0.030
		2000	0.99	0.985	0.050	0.010			2000	0.99	0.979	0.007	0.013
		2000	0.95	0.948	0.025	0.026			2000	0.90	0.889	0.055	0.056
			0.99	0.945	0.025	0.020				$0.95 \\ 0.99$	0.942 0.980	0.029 0.007	0.029
	10	1000	0.90	0.888	0.051	0.010		10	1000	0.99	0.980	0.063	0.013
	-3		0.95	0.940	0.027	0.033		10	1000	0.95	0.931	0.003	0.035
			0.99	0.979	0.007	0.015				0.99	0.975	0.009	0.03
		2000	0.90	0.888	0.056	0.057			2000	0.90	0.878	0.061	0.061
			0.95	0.941	0.028	0.030	1.0		-500	0.95	0.934	0.033	0.033
			0.99	0.980	0.007	0.013	16			0.99	0.977	0.008	0.015
	20	1000	0.90	0.879	0.054	0.067		20	1000	0.90	0.864	0.068	0.068
			0.95	0.934	0.029	0.037		-		0.95	0.923	0.038	0.038
			0.99	0.977	0.007	0.017				0.99	0.971	0.011	0.018
		2000	0.90	0.880	0.057	0.063			2000	0.90	0.868	0.066	0.066
			0.95	0.935	0.031	0.034				0.95	0.926	0.037	0.036
			0.99	0.977	0.007	0.016							

maximizing the quasi-likelihood (QL) with respect to the full parameter vector. To this purpose, we fix the cross-sectional dimension equal to ten assets and fit the MMReDCC model to three different datasets. An overview of the data being used is given in table A.12 in the Appendix. The first dataset comprises the assets used in Bauwens et al. (2016a) and includes series of daily realized covariance matrices estimated using five minute intraday returns over the period February 2001 until December 2009 (2242 observations); the second set is made up of some of the most liquid equities of the S&P 500 traded from October 1997 to July 2008 (2524 observations), while the last one consists of an arbitrarily selected subsample of assets from the dataset used in the work of Boudt et al. (2014). The latter contains series of daily realized covariance matrices obtained with the *CholCov* estimator over the period January 2007–December 2012 (1499 trading days). As already mentioned, the choice of the realized estimator is not an issue as the model can be fitted to any series of realized variance-covariance matrices as long as they are PDS. Finally, our analysis focuses on open-to-close covariance matrices, whereby noisy overnight returns have not been included in the construction of the estimators. We refer to the cited papers for further details.

As suggested by a referee, the IMP estimator could also be used to provide accurate initial values for direct QML estimation leading to a reduction of the number of iterations needed to reach convergence and, hence, to substantial computational savings. In this spirit we also consider the additional estimator, denoted as IMP(+), obtained by performing one iteration of the one-step QL optimization, taking the IMP estimate as starting point.

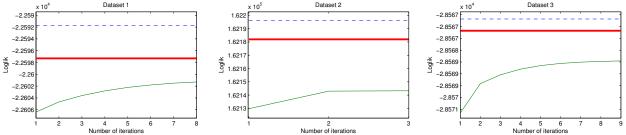
Estimation results for the MMReDCC model parameters by the QML, IMP and IMP(+) estimators are collected in Panel A of Table 8. In the three datasets considered, all methods appear to deliver similar estimates. Short term GARCH coefficients tend to be quite homogeneous across assets and generally significant; the same applies to the short term correlation estimates. As for the parameters driving the long term component, it can be noticed that the estimated θ and ω coefficients are regularly lower for the IMP than for the QML method. This is in line with the prevailing negative bias found in the simulation study. Coming to the analysis of the maximized quasi log-likelihood values, it can be seen that, as expected, the QMLE returns the highest QL value for all the datasets, but those obtained by the IMP estimator are very close, and the gap never exceeds 0.04% in relative terms. The IMP(+) further reduces the discrepancy but its contribution is as small as 0.014% on average, thus far from impressive.

The bottom line of Panel A reports test statistics and corresponding p-values of a score test (ST) performed to assess convergence of the IMP and IMP(+) estimators. Namely, we test the null hypothesis that $\psi^* = \mathbf{0}$ in the unrestricted model parameterized by $\psi = \hat{\psi}_M + \psi^*$ where $\hat{\psi}_M$ denotes the estimate of ψ obtained by estimation method M. In practice ψ^* can be interpreted as the bias potentially affecting the estimated ψ in case of lack of convergence of the IMP and IMP(+) algorithms. In order to double check our results, the test is repeated for the QML estimator. The null is accepted in all cases. This result is confirmed by Figure 2 that compares the values of the QL function recorded for the IMP estimator in each iteration (continuous thin line) with the maximum obtained by direct maximization of the QL function (dotted line) and by the IMP(+) estimator (continuous thick line). The plot shows that the IMP algorithm increases the value of the QL function at each step monotonically converging to a value which is very close to the maximum yielded by the direct QML estimator.

Finally, Panel B of Table 8 provides further information on the performance of the estimators measured in terms of mean, standard deviation, first (Q1) and third (Q3) quantiles of the estimated conditional variance, covariance and correlation series. Furthermore, to gain deeper insight on the practical impact that the choice of the estimation algorithm can have on risk management applications, the comparison is extended to the estimated conditional variances of the equally weighted portfolio returns. In general, the

distribution of the estimated series do not appear to be very sensitive to the estimation method adopted. The most sizeable differences are observable between the estimated conditional variances and covariances of Dataset 3. Our intuition is that a relevant role in explaining these differences is played by the sensibly shorter time series length of Dataset 3: 1499 days versus 2242 for Dataset 1, and 2524 for Dataset 2. Given the higher unconditional volatility level of Dataset 3, compared to 1 and 2, it is also tempting to identify this as a determinant of the observed discrepancies between IMP and QML estimates. However, in general, we prefer to be cautious about this issue since, working with real data, several other factors could be in action. For example, model misspecification could differently affect, in an unknown way, the IMP and QML estimators (see e.g. Francq et al. (2011)). Nevertheless, the discrepancy becomes negligible if we focus on conditional correlations and, in particular, on portfolio volatility which is the main quantity of interest for risk management applications.

Figure 2: The figure shows the log-likelihood value at the maximum (y-axis) achieved by the IMP (continuous thin line), IMP(+) (continuous thick line) and 1-step QML (dotted line), for each of the considered datasets. The number of iterations needed for the IMP optimization to converge is given on the x-axis (8 for Dataset 1, 3 for Dataset 2 and 9 for Dataset 3).



6.2 Forecasting performance

In this subsection we push the analysis to higher dimensions, with the aim of assessing the usefulness of the MMReDCC model in a forecasting exercise. As benchmarks we consider the consistent RDCC (cRDCC) model of Bauwens et al. (2012) as the closest competitor and a simple Exponentially Weighted Moving Average (EWMA) model. The EWMA predictor appears a natural candidate due to its widespread diffusion among practitioners and in risk management systems like RiskMetrics. If applied to series of daily realized covariance matrices, it is defined by

$$S_t = (1 - \lambda)C_{t-1} + \lambda S_{t-1},$$

where the λ parameter is set equal to the value 0.94 (see also Golosnoy et al. (2012)).

On the other hand, the choice of the cRDCC as a benchmark is supported by two main reasons. First, it assumes that conditional volatilities and correlations mean revert to constant quantities, thus it can be considered as a simplified version of the MMReDCC model despite not being formally nested in it. Second, the findings of Boudt et al. (2014) show that the cRDCC model favorably compares with some widely used competitors, such as the HEAVY (Noureldin et al. (2012)) and the cDCC (Aielli (2013)) model, in forecasting Value-at-Risk. In order to estimate the cRDCC in high dimension, we apply a three stage QML estimation procedure as suggested by Bauwens et al. (2012), where the constant long term covariance

Table 8: Application I. In-sample comparison

Panel A shows parameter estimates with corresponding standard errors in brackets for each of the estimators employed and the three datasets considered (see table A.12 in the Appendix). IMP(+) denotes results achieved after one iteration of the one-step QL optimization, taking the IMP estimate as starting point. The last two rows respectively report the log-likelihood (Loglik) values at the maximum and Score test (ST) statistics with corresponding p-values in brackets. Panel B reports summary statistics for the estimated series of volatilities (Vol), covariances (Cov) and correlations (Corr) across estimators and datasets. The properties of the volatilities (Portf. vol) of the n-dimensional equally weighted portfolios constructed using the estimated conditional covariance matrices are also compared. The number of in-sample observations is 2242 for Dataset 1, 2524 for Dataset 2 and 1499 for Dataset 3. Realized series of the assets comprised in Dataset 2 multiplied by 10000.

		DAT	TASET	1					Da	TASET	2				DATA	ASET 3	3	
PANEL	A: P	ARAM	ETER	ESTIM	ATES													
	ML	Т	MP	IM	P(+)		0	$\overline{\mathrm{ML}}$	т	MP	TMI	P(+)	C	QML	I	MP	IMI	P(+)
$\frac{\gamma_i}{\gamma_i}$	δ_i	γ_i	δ_i	γ_i	$\frac{1}{\delta_i}$	-	$\frac{Q}{\gamma_i}$	$\frac{\delta_i}{\delta_i}$	γ_i	$\frac{\delta_i}{\delta_i}$	γ_i	$\frac{\delta_i}{\delta_i}$	γ_i	$\boldsymbol{\delta}_i$	γ_i	$\boldsymbol{\delta}_i$	γ_i	$\boldsymbol{\delta}_i$
0.35	0.60	0.34	0.59	0.37	0.55		0.12	0.88	0.10	0.85	0.09	0.82	0.18 (0.07)	0.75 (0.06)	0.18 (0.16)	0.75 (0.07)	0.17 (0.09)	0.75 (0.05)
0.10) 0.34	(0.03) 0.58	(0.06) 0.31	0.03 0.60	0.15 0.33	(0.08) 0.58		$0.04) \\ 0.32$	0.19 0.80	(0.06) 0.33	0.10) 0.83	(0.03) 0.29	0.15 0.82	0.23	0.69	0.23	0.69	0.24	0.68
(0.38)	(0.08)	(0.76)	(0.05)	(0.86)	(0.07)		(0.15)	(0.18)	(0.07)	(0.12)	(0.29)	(0.18)	(0.20)	(0.04)	(0.90)	(0.05)	(0.92)	(0.04)
0.41 (0.04)	0.57 (0.06)	0.40 (0.03)	0.52 (0.05)	0.41 (0.05)	0.51 (0.09)		0.33	0.61 (1.01)	0.28 (0.07)	0.55 (0.10)	0.33 (0.30)	0.52 (0.43)	0.24 (0.04)	0.62 (0.06)	0.25 (0.16)	0.62 (0.21)	0.25 (0.06)	0.61 (0.09)
0.43	0.53	0.38	0.49	0.41	0.48	ì	0.26	0.43	0.24	0.41	0.28	0.38	0.20 (0.05)	0.67 (0.07)	0.19 (0.06)	0.69 (0.07)	0.20 (0.07)	0.68 (0.06)
0.06 0.37	(0.06) 0.49	0.04 0.37	(0.06) 0.49	(0.06) 0.40	(0.07) 0.48	,	(0.03) 0.46	0.18 0.18	(0.06) 0.49	0.01 0.23	(0.12) 0.50	0.06 0.22	0.20	0.60	0.21	0.65	0.20	0.59
(0.05)	(0.05)	(0.03)	(0.49)	(0.05)	(0.06)		(0.40)	(0.09)	(0.14)	(0.23)	(0.09)	(0.06)	(0.06)	(0.09)	(0.11)	(0.12)	(0.06)	(0.10)
0.34 (0.05)	0.65 (0.12)	0.32 (0.04)	0.61 (0.06)	0.33 (0.06)	0.60 (0.06)		0.35 0.14)	0.76 (0.25)	0.34 (0.20)	0.79 (0.28)	0.35 (0.15)	0.78 (0.20)	0.18 (0.11)	0.69 (0.20)	0.18 (0.09)	0.73 (0.13)	0.19 (0.10)	0.68 (0.18)
0.40 (0.05)	0.52 (0.11)	0.42 (0.04)	0.51 (0.05)	0.44 (0.06)	0.49 (0.10)		0.43	0.52	0.23 (0.10)	0.44	0.31 (0.10)	0.36	0.15 (0.09)	0.68 (0.23)	0.14 (0.08)	0.74 (0.19)	0.16 (0.10)	0.66 (0.23)
0.47 (0.04)	0.43 (0.04)	0.45	0.40	0.45 (0.04)	0.40	ì	0.45	0.72	0.43	0.70	0.45	0.68	0.18	0.75 (0.16)	0.18 (0.30)	0.75 (0.40)	0.18	0.75 (0.16)
0.31	0.61	0.31	0.59	0.32	0.57	,	$0.21) \\ 0.18$	0.17 0.59	0.16 0.16	0.01 0.63	0.19 0.20	0.60	0.18	0.74	0.30	0.75	0.08	0.74
(0.06)	(0.08)	(0.04)	(0.05)	(0.04)	(0.08)	((0.06)	(0.19)	(0.15)	(0.04)	(0.17)	(0.13)	(0.10)	(0.27)	(0.14)	(0.23)	(0.20)	(0.50)
0.34 (0.06)	0.55 (0.09)	0.31 (0.04)	0.58 (0.06)	0.35 (0.05)	0.56 (0.08)		0.43 (0.11)	0.36 (0.09)	0.47 (0.17)	0.27 (0.01)	0.48 (0.12)	0.28 (0.10)	0.14 (0.04)	0.78 (0.05)	0.14 (0.06)	0.80 (0.10)	0.14 (0.04)	0.78 (0.05)
α	$\boldsymbol{\beta}$	α	\boldsymbol{eta}	α	\boldsymbol{eta}		α	$\boldsymbol{\beta}$	α	$\boldsymbol{\beta}$	α	$\boldsymbol{\beta}$	α	β	α	β	α	β
0.07 (0.02)	0.91 (0.08)	0.08 (0.01)	0.88 (0.06)	0.07 (0.02)	0.88 (0.08)		0.05 (0.01)	0.86 (0.16)	0.04 (0.01)	0.89 (0.10)	0.05 (0.00)	0.87 (0.11)	0.01 (0.00)	0.80 (0.10)	0.01 (0.00)	0.88 (0.05)	0.01 (0.00)	0.77 (0.05)
θ	ω	θ	ω	$\boldsymbol{\theta}$	ω		θ	ω	θ	ω	θ	ω	θ	ω	$\boldsymbol{\theta}$	ω	θ	ω
0.88 (0.01)	4.57 (0.01)	0.83 (0.00)	4.22 (0.01)	0.87 (0.00)	5.69 (0.03)		0.91 (0.01)	3.67 (0.02)	0.88 (0.02)	$\frac{2.91}{(0.07)}$	0.90 (0.06)	3.46 (0.19)	0.84 (0.02)	5.52 (1.58)	0.81	5.16 (0.57)	0.82 (0.01)	5.56 (0.44)
Lo	glik	\mathbf{L}	oglik		glik	_	Lo	glik	L	oglik	Lo	glik		oglik	()	oglik	/	glik
	2592		22601		2597			2196		52143		2180		28567		28568		8567
-	\mathbf{ST}		ST		ST			ST		\mathbf{ST}		\mathbf{T}		ST		$\overline{\mathbf{ST}}$	5	T
	.001		0.026 (1.00)		0.001 .00)			.103 1.00)		1.00)		290 .00)	(0.000 (1.00)	0	.030	0.	001

PANEL	B: Pr	OPERT	ES OF	ESTIMATE	D SERIES									
		QML	IMP	IMP(+)			\mathbf{QML}		IMP(+)			QML	IMP	IMP(+)
Vol	mean	2.98	3.06	3.14	Vol	mean	3.60	3.59	3.91	Vol	mean	17.33	12.83	11.75
	std	5.70	5.84	5.89		std	8.66	9.03	9.50		std	23.93	19.86	18.35
	Q1	0.70	0.70	0.74		Q(1)	0.95	1.07	1.19		Q1	4.38	3.30	3.07
	Q3	2.60	2.69	2.78		Q(2)	4.12	4.28	4.70		Q3	12.19	11.15	10.23
Cov	mean	1.20	1.24	1.26	\mathbf{Cov}	mean	0.67	0.71	0.73	Cov	mean	7.16	5.20	4.81
	std	2.45	2.47	2.49		std	1.53	1.85	1.96		std	8.94	7.03	6.53
	Q1	0.20	0.21	0.22		Q(1)	0.24	0.26	0.28		Q1	1.85	1.23	1.14
	Q3	1.03	1.09	1.10		Q(2)	0.81	0.87	0.92		Q3	7.17	5.21	4.76
Corr	mean	0.37	0.39	0.38	Corr	mean	0.26	0.27	0.25	Corr	mean	0.42	0.42	0.42
	std	0.10	0.10	0.10		std	0.12	0.13	0.12		std	0.08	0.09	0.09
	Q1	0.30	0.31	0.31		Q(1)	0.17	0.17	0.17		Q1	0.36	0.35	0.35
	Q3	0.44	0.45	0.44		$\vec{Q}(2)$	0.35	0.36	0.35		Q3	0.48	0.48	0.48
Portf.	mean	0.95	0.97	0.99	Portf.	mean	0.91	0.92	0.95	Portf.	mean	2.29	2.10	2.02
vol	std	0.69	0.69	0.69	vol.	std	0.38	0.37	0.37	vol	std	1.40	1.25	1.20
	Q1	0.52	0.53	0.54	701.	Q(1)	0.60	0.62	0.63		Q1	1.47	1.20	1.16
	Q3	1.10	1.13	1.14		Q(1) $Q(2)$	1.10	1.11	1.13		Q3	2.63	2.41	2.30

matrix is consistently targeted by the unconditional covariance. This drastically reduces the number of parameters to be estimated to 2n + 2.

The dataset, also used by Laurent et al. (2012), contains realized covariance matrices based on intraday returns computed from 6-minute intervals last mid-quotes of 46 assets traded in the NYSE and NASDAQ over the period January 5, 1999 to November 14, 2008, for a total of 2483 observations.

Table 9 reports parameter estimates obtained by fitting the MMReDCC and cRDCC models over the full sample period. As emerges from Panel A, the MMReDCC outperforms the cRDCC in terms of the AIC and BIC criteria, which are both minimized for the MMReDCC. The univariate GARCH(1,1) parameters $\bar{\gamma}$ and δ , reported in averaged values across series, largely agree with each other, while the correlation estimates are slightly different across the two models, with the cRDCC showing a higher level of persistence.

To closely examine the difference in the fit of the models, consider the estimated conditional correlations between two representative pairs of stocks. The first, presented in the upper panel of Figure 3, includes two financial assets: American Express (AXP) and Bank of America (BAC), while the second pair, in the lower panel, includes stocks from different sectors, i.e. McDonald's (MCD) and Wells & Fargo (WFC). In general the correlations returned by the MMReDCC model appear to be characterized by more pronounced fluctuations. At the beginning of the sample the correlation paths from the two models evolve around the same mean level while at the burst of the dot-com bubble in 2002 the MMReDCC correlations appear to be characterized by a positive level shift which is not present in the cRDCC series. For the reminder of the sample the cRDCC correlations are on average lower than those obtained from the MMReDCC. Given the close similarity between the models, this can be reasonably explained by the fact that the parameters θ and ω driving the long term (co)volatilities dynamics of the MMReDCC allow for a higher flexibility of the model and consequently for a better responsiveness of correlations in periods of pronounced market volatility.

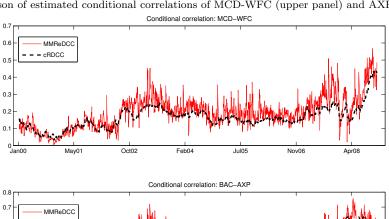


Figure 3: Comparison of estimated conditional correlations of MCD-WFC (upper panel) and AXP-BAC (lower panel).

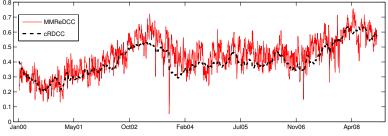


Table 9: Application II. Full sample estimates and implemented loss functions

Panel A reports full sample estimates from the MMReDCC and cRDCC model, where $\bar{\gamma}$ and $\bar{\delta}$ are averaged across the n series. AIC and BIC criteria have been rescaled by the number of observations. Panel B contains the loss functions chosen to evaluate the models forecasting ability. S_t denotes the predicted conditional covariance matrix while C_t is the 6-minute realized measure chosen as proxy for the latent covariance matrix.

Panel A:	Full sample estimates	
	MMReDCC	crdcc
$ar{\gamma}$	0.381 (0.087)	$0.373 \atop (0.180)$
$\bar{\delta}$	$0.543 \atop (0.110)$	$0.551 \\ (0.201)$
α	$0.016\atop (0.001)$	$0.020 \ (0.005)$
β	$0.950 \atop (0.002)$	$0.974 \ (0.007)$
θ	$0.761 \atop (0.027)$	
ω	$\frac{3.278}{(0.785)}$	
Loglik	787304	683817
AIC	-633	-617
BIC	-630	-616
PANEL B: I	LOSS FUNCTIONS	
ST	Stein	$\operatorname{tr}(S_t^{-1}C_t) - \log S_t^{-1}C_t - n$
vND	von Neumann Divergence	$\operatorname{tr}\left(C_{t} \log C_{t} - C_{t} \log S_{t} - C_{t} + S_{t}\right)$
QLIK	Qlike	$\log S_t + \operatorname{tr}\left(S_t^{-1}C_t\right)$

To determine whether the MMReDCC model can lead to gains in forecasting accuracy we compute predictions of the conditional covariance matrix of daily returns at 1, 5, 10 and 20 steps-ahead making use of the bootstrap procedure explained in Section

The forecasting period is characterized by drastic changes in volatility dynamics, as emerges from the summary statistics given in table A.13 in the Appendix. To better analyze to what extent this impacts on the performance of the models, we break the evaluation sample into two sub-samples. Their differences can be visualized by looking at Figure 4, which shows the realized variance of the equally weighted portfolio made of the 46 assets used in the application. The upper panel spans the period from November, 2004 until end of June, 2007, where the market experiences a situation of stability after the turmoil of the 2000-2003 dot-com bubble. On the other hand, the period from July, 2007 to November, 2008, highlighting a widespread turbulence on the market, coincides with the burst of the subprime financial crisis which reaches its peak with the collapse of Lehman Brothers in September 2008. During the last four months of the latter sub-sample, the unconditional volatility of the portfolio is roughly ten times higher than over the first sub-period.

The comparison of the models forecasting ability is performed using the consistent loss functions defined in Panel B of Table 9, for which we report averaged values over the two out-of-sample periods considered. The term *consistent* is used according to Laurent et al. (2013).

The test of Giacomini and White (2006) (GW) is used to examine the relative performance of the MMReDCC model with respect to the cRDCC and the EWMA. Namely, for each loss function L, the loss differential at time t is denoted as $\delta_t = L(C_{t+h}, S_{t+h|t}^{MMReDCC}) - L(C_{t+h}, S_{t+h|t}^{benchmark})$, where C_t is

the 6-minute realized covariance chosen as proxy for the true matrix. This difference is expected to be zero if neither of the models is superior, otherwise, negative (positive) values correspond to a superior forecasting performance of the MMReDCC (benchmark). In addition, consistently with the in-sample analysis performed in Section 6.1, we also assess, using the univariate version of the QLIK loss function, the ability of the different models to accurately predict the volatility of an equally weighted portfolio including all the 46 assets. As given by Patton (2011), the formula of the QLIK loss function for the volatility of the i-th asset is

$$QLIK_t = log(S_{ii,t}) + \frac{C_{ii,t}}{S_{ii,t}},$$

whereas its portfolio version is obtained by replacing $C_{ii,t}$ and $S_{ii,t}$ by their portfolio equivalents. The null of equal predictive accuracy is then tested by means of the following t-statistic

$$GW = \sqrt{T - \tau + h} \frac{\sum_{t=\tau+h}^{T} \delta_t}{\sqrt{\operatorname{avar}\left(\sum_{t=\tau+h}^{T} \delta_t\right)}},$$

and the Newey-West estimator is used to consistently estimate the long run variance of $\sum_{t=\tau+h}^{T} \delta_t$.

Table 10 shows the resulting average loss differences summarized by horizon. The value achieved by either the EWMA or the cRDCC is in italic if the model is favored by the GW test, in bold if the test favors the MMReDCC or underlined if the test is indecisive.

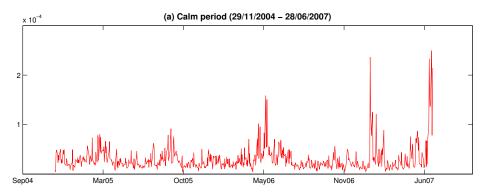
According to Panel A, the MMReDCC model is not leading to particularly impressive gains in fore-casting accuracy compared to the two benchmarks. When focusing on direct evaluation of forecasts of the whole RC matrix, the cRDCC is prevailing at the shortest horizon according to all loss functions, while for h > 1 they fail to point towards a unique winner as the overall performance of the models is pretty similar and the test is often inconclusive. Despite being the simplest model, the EWMA is found to perform no worse than the other two and to be preferred twice by the vND over the MMReDCC. Considering that the period covered by Panel A is characterized by a relatively small and slow-moving market volatility, these results are probably not surprising for two reasons. First, it is known that in such circumstances highly parameterized sophisticated models suffer from additional parameter uncertainty, thus being more heavily penalized than model featuring simple parameterizations. Second, when the underlying process exhibits smooth dynamics, it is more complicated for the MMReDCC model to disentangle the different volatility components, thus suggesting that accurate predictions can be obtained by employing models that do not necessarily account for time-varying long run levels.

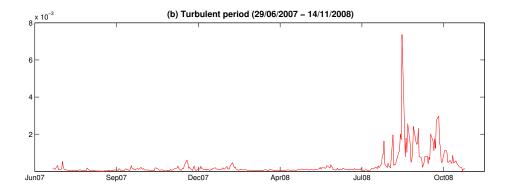
As we move to analyze the results in Panel B, the situation is quickly reversed. The cRDCC is still minimizing two out of three loss functions at the one-step horizon, but in all other cases it is evident that, whenever the models predictive abilities can be distinguished, the GW test decides in favor of the MMReDCC. The over-performance of the MMReDCC is particularly strong at the 20-day horizon, when it delivers the optimal covariance forecasts according to the whole set of losses.

A slightly different situation arises when we move to the analysis of portfolio volatility forecasts. In this case the forecasting performance of the MMReDCC model appears to be more stable over time. In period A, at the 1-day horizon the MMReDCC is outperforming the EWMA and doing not significantly worse than the cRDCC. At longer horizons, it is always prevailing over its competitors, the only exception being represented by the CRDCC, for which at horizon 20 we cannot reject the null of equal predictive

Figure 4: Equally weighted portfolio daily realized variance

The figure shows the daily realized variance over the forecasting period of the equally wighted portfolio composed of the 46 assets used in the empirical application and listed in Table 13. The sample is divided into a more calm period (upper panel, 650 observations) and a more volatile period (lower panel, 350 observations).





ability. In period B, again the worst performance is recorded for the 1-day horizon but, for longer horizons, the MMReDCC is performing significantly better than its competitors in all cases except for the 10-day horizon when the comparison with the EWMA result is indecisive.

Table 11 offers a closer inspection of the models relative performance by reporting GW test results across univariate (co)volatilities and correlations. For sake of space, only the QLIK case is considered. Each panel of the table records the number of series (out of 1081 (co)volatilities and 1035 correlations) for which the test favors the MMReDCC, one of the benchmarks or gives no decision. Results are mostly in accordance with those achieved for the whole covariance matrix and stress the evidence that in periods of calm (Panel A) there is almost no benefit from employing the MMReDCC model for (co)volatility prediction. The gain in terms of correlations is marginal and only achieved with respect to the EWMA. On the other hand, sensibly better results are obtained over the final period (Panel B), both in terms of (co)volatility and correlation dynamics. Noticeably, the number of cases favoring the MMReDCC increases with h and becomes striking already at h = 10.

Overall, the main message we can get from these empirical results is that while constant long term models may be preferred in moderately volatile time periods, the benefits from the MMReDCC model can be fully appreciated in periods of market instability. This is easily explained by considering that, in calm periods, such as the one immediately preceding the 2008 financial crisis, the expected volatility and

correlation level are fairly constant over time. In such a framework the cRDCC model offers a simple and effective tool for keeping track of the realized covariance dynamics and differences in the predictive ability of the two models are mainly due to estimation noise. On the other hand, in periods of market instability where calm and turbulent periods alternate, the long run levels of realized volatilities and correlations are characterized by more pronounced excursions. In these cases, the flexibility of the MMReDCC model assures a higher responsiveness and more reliable out-of-sample forecasts than the cRDCC which is bound by the assumption of a constant long run level.

Table 10: Multi-step-ahead forecast evaluation

The table reports averaged values of the loss functions listed in Table 9. Results are reported across the out-of-sample period divided into a more calm period (Panel A, November 2004 to July 2007) and a more turbulent period (Panel B, July 2007 to November 2008). In the last row of each panel we also report the averaged QLIK of the out-of-sample variance of the equally weighted portfolio obtained using the predicted covariance matrices of the models. For each horizon, we perform pairwise Giacomini-White (GW) tests for the significance at 5% level of the loss difference between the MMReDCC and each benchmark: the competitor is in italic if it is favored by the test, in bold if the MMReDCC is favored and underlined if the test is indecisive.

	11	Iorizon 1			н	orizon 10		Horizon 20				
				l .	Iorizon 5		I			i		
	MMReDCC	EWMA	cReDCC	MMReDCC	EWMA	cReDCC	MMReDCC	EWMA	cReDCC	MMReDCC	EWMA	cReDCC
PANEL A	: 29-11-2004/0	01-07-2007										
ST	37.37	37.52	36.56	38.08	38.62	38.39	38.80	39.24	39.45	39.05	40.01	41.43
vND	0.003	0.003	0.003	0.003	0.003	0.003	0.003	0.003	0.003	0.003	0.003	0.004
QLIK	-386.62	<u>-386.46</u>	-387.43	-385.74	-385.20	-385.43	-385.02	<u>-384.58</u>	-384.38	-383.96	<u>-383.79</u>	-382.38
Portf. vol	-9.69	-9.55	<u>-9.69</u>	-9.75	-9.49	-9.70	-9.789	-9.48	-9.75	-9.83	-9.46	<u>-9.84</u>
PANEL B	3: 02-07-2007/1	4-11-2008										
ST	40.12	43.88	39.29	48.03	50.04	49.75	52.76	54.38	58.05	63.08	69.28	72.25
vND	0.023	0.026	0.025	0.030	0.032	0.033	0.043	0.047	0.044	0.045	0.054	0.054
QLIK	-338.75	<u>-338.00</u>	-342.58	-337.35	-332.04	-335.33	-328.48	<u>-327.86</u>	-324.19	-318.29	-312.09	-309.12
Portf. vol	-7.57	-7.43	-7.69	-7.70	-7.41	-7.34	-7.61	<u>-7.37</u>	-6.88	-7.16	-6.72	-5.88

7 Conclusions

The estimation procedure proposed in the paper allows to extend the range of applicability of the MM-ReDCC model to large dimensional portfolios such as those encountered in risk management practice. In order to reach this objective, we face two well-known challenges in multivariate time series modeling, namely high-dimensional estimation and multi-step ahead forecasting.

To face the former challenge, we implement a feasible estimation procedure, the Iterative Moment based Profiling (IMP) algorithm. It profiles out the parameters of the scale MIDAS intercept matrix and iteratively maximizes the likelihood in terms of the other parameters of interest. Whilst not providing an asymptotic inference theory for this method, we investigate the finite sample properties of the estimator via a simulation study, which demonstrates that the IMP estimator delivers accurate estimates irrespective of the initialization method employed. We also compare the one-step QML and IMP estimators on real data sets of small dimension (ten) and find that not only the two estimators deliver very similar in-sample estimates, but also that the loss of the IMP in terms of likelihood values can be considered as negligible. Another application illustrates the usefulness of the IMP algorithm when the model has to be fitted to high dimensional realized covariance matrices. In this respect, the IMP algorithm is reliable from the computational point of view and easy to implement despite the large number of parameters involved in

Table 11: GW test results across series

Unconditional Giacomini-White (GW) test results at 5% level of significance using the QLIK function. Each panel of the table records the number of series for which the MMReDCC is favored, for which there is no decision and for which one of the benchmarks is favored. Results are differentiated between conditional (co)volatilities (1081 series) and correlations (1035 series).

					·					
	(Co)ve	olatilities		Correlations						
PANEL	A: 29-11-2004	/01-07-2	2007							
Horizon	Favors MMReDCC	Indecisive	Favors B	Model B	Favors MMReDCC	Indecisive	Favors B	Model B		
1	155	732	194	EWMA	62	669	304	EWMA		
	24	447	610	cRDCC	87	522	426	cRDCC		
5	121	833	127	EWMA	89	882	64	EWMA		
	20	369	692	cRDCC	114	427	494	cRDCC		
10	33	948	100	EWMA	72	906	57	EWMA		
	37	356	688	cRDCC	213	503	319	cRDCC		
20	51	850	180	EWMA	118	877	40	EWMA		
	77	512	492	cRDCC	108	605	322	cRDCC		
PANEL	B: 02-07-2007	/14-11-2	2008							
Horizon	Favors MMReDCC	Indecisive	Favors B	Model B	Favors MMReDCC	Indecisive	Favors B	Model B		
1	41	853	187	EWMA	130	689	133	EWMA		
	5	187	889	cRDCC	266	627	142	cRDCC		
5	106	910	65	EWMA	78	911	46	EWMA		
	429	620	32	cRDCC	502	505	28	cRDCC		
10	198	883	0	EWMA	217	791	27	EWMA		
	739	340	2	cRDCC	567	454	14	cRDCC		
20	193	888	0	EWMA	339	687	9	EWMA		
	835	246	0	cRDCC	626	405	4	$_{\mathrm{cRDCC}}$		

the MMReDCC model. Given its flexibility, we fairly believe that it could be applied to datasets of even larger dimensions.

As regards the second challenge, we develop a bootstrap approach to the generation of multi-step-ahead predictions. In an application to a portfolio of forty-six stocks, we provide compelling evidence that the MMReDCC model is useful for out-of-sample forecasting purposes in periods of pronounced market volatility. If compared with existing multivariate competitors not accounting for time-varying long term dynamics, the MMReDCC is found to deliver the most accurate predictions especially at long term horizons, thus indicating the importance of allowing for a more flexible long run component.

A Descriptive statistics

Table 12: Descriptive statistics of daily realized variances used in Application I

The table reports descriptive statistics of daily realized variances of the assets included in Dataset 1, 2 and 3 used in the first empirical application. Realized variances of the assets comprised in Dataset 2 multiplied by 10000.

Symbol	Issue name	Mean	Max.	Min.	Std.dev.	Skewness	Kurtosis						
	Dataset	1: Februar	$ry, 2001 - \Gamma$	December,	2009								
AA	Alcoa	5.458	277.308	0.074	16.811	7.178	72.570						
AXP	American Express	5.055	176.478	0.112	11.094	7.529	84.686						
BAC	Bank of America	1.934	57.543	0.075	3.362	7.319	85.006						
KO	Coca Cola	2.455	43.106	0.084	3.412	4.724	36.234						
DD	Du Pont	2.073	115.378	0.126	4.155	13.296	288.066						
GE	General Electric	4.944	160.241	0.294	8.935	7.635	92.124						
$_{\rm IBM}$	International Business Machines	4.420	201.879	0.077	9.154	8.536	133.699						
$_{ m JPM}$	JP Morgan	2.529	63.874	0.163	3.728	6.442	68.505						
MSFT	Microsoft	3.196	114.256	0.097	7.114	7.232	75.484						
XOM	Exxon Mobil	1.414	56.505	0.039	2.254	9.715	180.206						
	Dataset 2: May, 1997 – July, 2008												
ABT	Abbott Laboratories	3.831	249.408	0.197	8.588	17.264	397.922						
T	AT& T	5.490	458.044	0.166	14.953	17.145	412.001						
FISV	Fiserv	7.828	628.583	0.270	15.588	26.114	999.133						
ALL	Allstate Corporation	4.423	980.762	0.106	20.731	41.512	1934.757						
GPC	Genuine Parts Company	3.765	887.997	0.171	18.221	45.217	2180.553						
AFL	Aflac Incorporated	4.443	267.045	0.153	10.955	14.110	268.010						
AA	Alcoa	5.417	123.771	0.354	7.422	7.331	86.153						
GE	General Electric	3.973	366.830	0.131	11.481	20.633	559.319						
CTL	Century Link	4.472	687.135	0.217	18.814	24.783	775.201						
\mathbf{C}	Cytigroup Inc.	6.244	861.435	0.157	21.306	27.458	1036.670						
	Dataset	t 3: Januar	y, 2007 - D	ecember, 2	2012								
ACAS	American Capital	8.576	331.786	0.060	20.844	7.226	78.667						
AET	Aetna	8.163	771.525	0.109	26.593	17.882	467.969						
AFL	Aflac Incorporated	9.113	675.348	0.133	27.345	13.811	284.791						
AIG	American International Group	8.799	555.098	0.103	26.382	11.459	185.778						
AIZ	Assurant	8.613	325.167	0.101	23.230	7.712	79.082						
ALL	The Allstate Corporation	8.213	543.714	0.186	24.593	11.277	189.052						
AMP	Ameriprise Financial	7.679	264.761	0.129	17.790	6.098	54.262						
AXP	American Express Company	8.076	945.750	0.095	30.571	21.795	618.891						
BAC	Bank of America	8.450	332.586	0.130	22.830	8.458	96.824						
BBT	BB&T Corporation	9.093	613.826	0.087	28.801	11.267	184.837						

Table 13: Descriptive statistics of daily realized variances used in Application II

The table reports descriptive statistics of daily realized variances of the assets used in the second empirical application, where the forecasting sample, spanning from November 29, 2004 to November 14, 2008, is divided into a calm period (650 observations) and a more turbulent period (350 observations) including the 2008 financial crisis. Realized volatilities multiplied by 10000.

Stock	Issue name	Mean	Max.	Min.	Std.dev.	Skewness	2007 (650 OBSERVATIONS) Kurtosis	_					
AAPL	Apple	3.114	44.664	0.257	2.997	6.109	68.647						14, 2008 (350 observation
ABT	Abbott	1.040	11.301	0.151	0.818	4.773	45.820	Mean	Max.	Min.	Std.dev.	Skewness	Kurtosis
AXP	American Express	0.876	10.932	0.072	1.038	5.715	44.530	8.579	109.719	0.609	12.570	4.249	26.370
BA	The Boeing Comp.	1.147	5.444	0.254	0.767	2.388	10.830	3.225	81.740	0.258	5.702	8.409	106.373
BAC	Bank of America	0.701	13.063	0.117	0.764	8.737	120.508	12.572	312.208	0.838	22.702	7.818	92.250
BMY	Bristol-Myers Squibb Comp.	1.270	20.256	0.179	1.286	7.526	90.830	5.151	57.291	0.532	7.796	3.231	15.171
BP	BP b.l.c.	0.751	3.873	0.179	0.448	2.482	12.914	14.876	276.824	0.279	26.233	4.942	38.722
C	Citigroup Inc.	0.731	12.850	0.133	0.963	7.033	72.020	4.259	87.928	0.242	6.620	6.861	76.824
CAT							19.679	3.906	65.784	0.219	6.626	4.212	28.869
	Caterpillar	1.605	11.470	0.303	1.233	3.277		21.287	1015.764	0.519	64.196	11.716	171.168
CL	Colgate-Palmolive	0.800	11.800	0.121	0.688	8.066	112.163	6.805	118.706 89.214	0.566 0.243	11.322	4.502 10.719	33.594
CSCO	Cisco Systems	1.552	11.784	0.189	1.014	3.324	24.630	2.628 6.178	114.330	0.243	5.673 9.424	5.839	157.531 55.640
CVX	Chevron Corp.	1.679	14.566	0.289	1.349	3.580	24.108	6.200	166.296	0.478	12.609	5.839 7.428	55.040 82.139
DELL	Dell	1.756	14.185	0.242	1.298	2.927	19.247	7.323	143.320	0.149	12.009	6.050	55.752
DIS	Walt Disney	1.014	7.920	0.201	0.712	3.932	30.039	5.089	118.243	0.453	9.420	6.197	63.696
EK	Eastman Kodak	1.416	22.304	0.179	1.642	6.306	60.391	6.751	134.678	0.455	11.362	5.373	50.263
EXC	Exelon	2.841	24.425	0.401	2.296	3.978	28.797	27.900	1981.687	0.937	116.942	13.976	226.720
F	Ford Motor	1.307	9.113	0.083	0.947	2.928	16.728	5.261	71.372	0.937	7.107	4.048	27.759
FDX	FedEX Corp.	0.663	3.940	0.126	0.447	3.009	16.528	6.789	97.782	0.292	13.465	4.100	23.033
GE	General Electric	1.305	6.982	0.181	0.858	2.407	11.664	7.993	160.418	0.495	11.651	7.441	87.734
GM	General Motors	0.666	6.577	0.105	0.589	4.342	32.564	2.303	39.958	0.208	3.666	4.777	38.049
HD	The Home Depot	1.306	10.663	0.173	1.003	4.422	34.275	5.686	139.350	0.541	10.774	6.729	72.384
HNZ	HNZ Group	0.796	4.691	0.128	0.549	2.948	15.566	4.494	85.792	0.490	7.507	5.156	44.724
HON	Honeywell	1.541	7.739	0.332	0.840	1.937	9.764	5.841	76.334	0.478	7.396	4.103	29.515
IBM	International Business Machines	0.495	2.679	0.063	0.330	2.193	10.384	2.034	59.372	0.086	4.539	7.056	77.545
INTC	Intel Corp.	0.455	13.492	0.140	0.939	5.838	59.503	14.577	234.008	0.332	25.147	4.980	34.276
JNJ	Johnson & Johnson							2.874	101.443	0.189	6.550	10.331	148.976
		0.577	4.866	0.076	0.366	3.806	34.495	3.471	89.880	0.265	6.457	7.790	94.853
JPM	JP Morgan	0.962	9.037	0.142	0.654	4.891	49.285	3.730	148.108	0.273	8.824	12.878	207.094
KO	Coca Cola	1.143	8.119	0.197	0.816	2.961	17.698	3.849	60.731	0.286	6.388	4.156	26.768
LLY	Eli Lilly and Co.	0.884	8.232	0.099	0.702	5.275	47.421	5.405	153.458	0.532	10.592	8.776	113.275
MCD	Mc'Donald	1.456	39.785	0.139	2.373	10.527	141.696	42.394	1836.085	1.213	156.907	8.427	82.761
MMM	3M Company	1.769	22.744	0.346	2.065	6.197	53.214	4.559	46.751	0.385	6.309	3.449	17.267
MOT	Motorola	0.892	4.629	0.179	0.556	2.350	11.471	5.723	61.006	0.665	8.031	3.857	20.906
MRK	Merck & Co.	1.816	14.715	0.366	1.130	3.854	35.605	2.905	138.670	0.168	8.233	13.189	213.668
MS	Morgan Stanley	0.608	4.486	0.118	0.408	3.538	24.998	3.556	63.957	0.305	5.699	4.909	41.144
MSFT	Microsoft	1.094	19.804	0.146	1.058	9.820	157.073	2.770	123.527	0.196	7.582	12.047	186.371
SLB	Schulumberger Limited	0.679	6.771	0.079	0.530	4.601	38.636	7.569	196.766	0.648	13.960	8.415	102.982
Т	AT&T	2.710	22.356	0.423	1.834	3.716	30.143	10.437	166.001	0.494	15.246	4.652	36.751
TWX	Time Warner	3.020	13.708	0.206	1.905	1.995	8.992	5.943	156.416	0.276	11.229	7.837	95.552
UN	Unilever	1.024	9.537	0.117	0.824	4.180	31.694	6.341	114.383	0.316	10.664	4.681	36.406
VZ	Verizon Communications	1.184	48.463	0.241	2.020	20.043	463.495	2.333	41.487	0.215	3.697	4.803	40.510
ORCL	Oracle Corp.	0.509	4.318	0.092	0.361	3.483	25.912	5.142	133.199	0.147	9.425	8.057	100.502
PEP	Pepsico	0.954	8.887	0.092 0.172	0.768	4.086	30.276	13.576	209.392	0.572	20.115	4.414	32.475
	•							3.700	92.274	0.234	6.315	8.804	114.371
PFE	Pfizer Inc.	0.693	8.324	0.075	0.695	5.557	47.417	5.506	188.347	0.331	12.581	9.788	132.406
PG	Procter & Gamble	0.914	7.693	0.131	0.632	4.083	34.957	6.288	182.259	0.653	12.009	9.676	134.541
QCOM	Qualcomm	1.414	11.781	0.246	1.121	4.085	29.777						
WFC	Well Fargo & Co.	1.790	44.518	0.243	2.202	12.661	226.808						

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